

Contents

Part I. Mohammed Dahleh Legacy

Legacy of Mohammed Dahleh	3
<i>Munther A. Dahleh</i>	
1 Childhood (1961-1979)	3
2 College Years (1979-1987)	5
3 Faculty at TAMU 1987-1990	6
4 The Decade at the University of California at Santa Barbara, 1991-2000	7
5 Mohammed's Sickness	10
6 Final Remarks	10
References	12

Part II. Control in Networks and Communications

A Control Theoretical Look at Internet Congestion Control ..	17
<i>Fernando Paganini, John Doyle, Steven H. Low</i>	
1 Introduction	17
2 Problem Formulation	18
3 Control design with linear scalable stability	22
4 Nonlinear laws and the equilibrium structure	27
5 Signaling requirements	29
6 Conclusion	30
References	30
Indelible Control	33
<i>Nicola Elia</i>	
1 Introduction	33
2 Problem Set-up	35
3 Channels as Model Uncertainty	36
4 Mean Square Closed Loop Stability	37
5 Minimal Channel Quality for Means Square Stability	38
6 Mean Square Stability Robustness to Structured Bounded Variance Uncertainty	39
7 Special Cases with only One Channel	41
8 Minimal Channel Quality for the Stabilization of a Pendubot	42
9 Conclusions	43
10 Appendix	44
References	45

Optimal Control Design under Structural and Communication Constraints	47
<i>Petros G. Voulgaris</i>	
1 Introduction	47
2 Specific Structures	48
3 Controller Parametrization	54
4 Optimal Performance	56
5 Conclusions and Discussion	59
References	60

Part III. Quantum Control

Fifteen Years of Quantum Control: from Concept to Experiment	65
<i>Anthony Peirce</i>	
1 Preamble	65
2 Molecular control	66
3 Design by intuition	66
4 The optimal control formulation	67
5 Uncertainty and robust design	69
6 Experiments and closed loop design	70
7 Concluding remarks	71
References	72
Directions in the Theory of Quantum Control	73
<i>Domenico D'Alessandro</i>	
1 Model of finite-dimensional quantum dynamics	73
2 Lie algebra structure, controllability and analysis of quantum systems	75
3 Methods for control	77
4 Conclusions	78
References	78

Part IV. Micro and Nano-scale Dynamics and Control

System tools applied to micro-cantilever based devices	83
<i>A. Sebastian, S. Salapaka, M. V. Salapaka</i>	
1 Introduction	83
2 Atomic Force Microscope: operating principles and features	84
3 Systems approach to the analysis of AFM dynamics	85
4 Broadband nanopositioning	90
5 Conclusions	96
References	97

Micro-scale sensors and filters utilizing non-linear dynamic response of single and coupled oscillators 101
Kimberly Turner, Rajashree Baskaran, Wenhua Zhang

1 Introduction 101

2 MEMS mass sensor 102

3 Electrostatically Coupled Oscillator filter 108

References 112

Part V. Connections with Biology

Feedback Regulation of the Heat Shock Response in *E. coli* ... 115
Hana El-Samad, Mustafa Khammash, Hiroyuki Kurata, John C. Doyle

1 Introduction 115

2 The Heat Shock Response: A Case Study 117

3 Conclusions and Future Work 126

References 127

Stem Cells from the Outside In 129
Marie Csete MD, PhD

1 Introduction: Stem cells 129

2 Oxygen levels 130

3 Conclusions 131

References 132

Optimal Image Interpolation 133
Steven Haker, Allen Tannenbaum

1 Introduction 133

2 Area-Preserving Diffeomorphisms 134

3 Formulation of Optimal Transport 135

4 Gradient Descent for Optimal Transport 136

5 Optimal Image Interpolation 137

6 Optical Flow 138

7 Computer Simulations 140

References 140

Part VI. Control and Identification

Robustness of Finite State Automata 147
Alexandre Megretski

1 System Models 148

2 Analysis and Design of FSA/IC Models 153

References 160

On the role of homogeneous forms in robustness analysis of control systems	161
<i>G. Chesi, A. Garulli, A. Tesi, A. Vicino</i>	
1 Introduction	161
2 Problem formulation and preliminaries	163
3 LMI-based conditions for the solution of the POFH problem	165
4 POFH problems in control system analysis	169
5 Conclusions	175
References	175
Control of Electromechanical Actuators: Valves Tapping in Rhythm	179
<i>Katherine Peterson, Anna Stefanopoulou, Yan Wang</i>	
1 Introduction	179
2 Variable Valve Timing Technology	180
3 Soft Landing Methodologies	181
4 Nonlinear Model	182
5 Control Analysis	183
6 Observer Design	187
7 Controller Design	189
8 Extremum Seeking Control	190
9 Conclusion	192
References	192
Learning complex systems from data: the Set Membership approach	195
<i>Mario Milanese and Carlo Novara</i>	
1 Introduction	195
2 The Nonlinear Set Membership approach	196
3 Nonlinear systems identification	201
4 Prediction of nonlinear systems	203
5 Conclusions	204
References	205
The mixing of state statistics	207
<i>Tryphon T. Georgiou</i>	
1 Introduction	207
2 The structure of state covariances	207
3 Mixing of state statistics	209
References	211
Controllability, integrability and ergodicity	213
<i>Igor Mezić</i>	
1 Introduction	213
2 Preliminaries	214
3 Hamiltonian systems in action-angle variables	218

4	Controllability by flatness	221
5	Ergodicity and controllability	223
6	Discussion and conclusions	226
7	Epilogue	227
	References	228