
Contents

Preface	IX
1 Arrays of Point and Line Sources, and Optimization	1
1.1 The Problem of Antenna Optimization	1
1.2 Arrays of Point Sources	2
1.2.1 The Linear Array	3
1.2.2 Circular Arrays	10
1.3 Maximization of Directivity and Super-gain	15
1.3.1 Directivity and Other Measures of Performance	15
1.3.2 Maximization of Directivity	19
1.4 Dolph-Tschebysheff Arrays	21
1.4.1 Tschebysheff Polynomials	22
1.4.2 The Dolph Problem	24
1.5 Line Sources	26
1.5.1 The Linear Line Source	30
1.5.2 The Circular Line Source	36
1.5.3 Numerical Quadrature	43
1.6 Conclusion	47
2 Discussion of Maxwell's Equations	49
2.1 Introduction	49
2.2 Geometry of the Radiating Structure	49
2.3 Maxwell's Equations in Integral Form	50
2.4 The Constitutive Relations	51
2.5 Maxwell's Equations in Differential Form	52
2.6 Energy Flow and the Poynting Vector	55
2.7 Time Harmonic Fields	56
2.8 Vector Potentials	58
2.9 Radiation Condition, Far Field Pattern	60
2.10 Radiating Dipoles and Line Sources	63
2.11 Boundary Conditions on Interfaces	68

2.12	Hertz Potentials and Classes of Solutions	70
2.13	Radiation Problems in Two Dimensions	73
3	Optimization Theory for Antennas	77
3.1	Introductory Remarks	77
3.2	The General Optimization Problem	80
3.2.1	Existence and Uniqueness	81
3.2.2	The Modeling of Constraints	84
3.2.3	Extreme Points and Optimal Solutions	88
3.2.4	The Lagrange Multiplier Rule	93
3.2.5	Methods of Finite Dimensional Approximation	96
3.3	Far Field Patterns and Far Field Operators	101
3.4	Measures of Antenna Performance	103
4	The Synthesis Problem	113
4.1	Introductory Remarks	113
4.2	Remarks on Ill-Posed Problems	115
4.3	Regularization by Constraints	121
4.4	The Tikhonov Regularization	127
4.5	The Synthesis Problem for the Finite Linear Line Source	133
4.5.1	Basic Equations	134
4.5.2	The Nyström Method	135
4.5.3	Numerical Solution of the Normal Equations	137
4.5.4	Applications of the Regularization Techniques	138
5	Boundary Value Problems for the Two-Dimensional Helmholtz Equation	145
5.1	Introduction and Formulation of the Problems	145
5.2	Rellich's Lemma and Uniqueness	148
5.3	Existence by the Boundary Integral Equation Method	151
5.4	L^2 -Boundary Data	157
5.5	Numerical Methods	163
5.5.1	Nyström's Method for Periodic Weakly Singular Kernels	164
5.5.2	Complete Families of Solutions	168
5.5.3	Finite Element Methods for Absorbing Boundary Conditions	174
5.5.4	Hybrid Methods	181
6	Boundary Value Problems for Maxwell's Equations	185
6.1	Introduction and Formulation of the Problem	185
6.2	Uniqueness and Existence	188
6.3	L^2 -Boundary Data	193

- 7 Some Particular Optimization Problems** 195
 - 7.1 General Assumptions 195
 - 7.2 Maximization of Power 197
 - 7.2.1 Input Power Constraints 198
 - 7.2.2 Pointwise Constraints on Inputs 202
 - 7.2.3 Numerical Simulations 204
 - 7.3 The Null-Placement Problem 211
 - 7.3.1 Maximization of Power with Prescribed Nulls 213
 - 7.3.2 A Particular Example – The Line Source 216
 - 7.3.3 Pointwise Constraints 219
 - 7.3.4 Minimization of Pattern Perturbation 221
 - 7.4 The Optimization of Signal-to-Noise Ratio and Directivity 226
 - 7.4.1 The Existence of Optimal Solutions 227
 - 7.4.2 Necessary Conditions 228
 - 7.4.3 The Finite Dimensional Problems 231

- 8 Conflicting Objectives: The Vector Optimization Problem** 239
 - 8.1 Introduction 239
 - 8.2 General Multi-criteria Optimization Problems 240
 - 8.2.1 Minimal Elements and Pareto Points 241
 - 8.2.2 The Lagrange Multiplier Rule 247
 - 8.2.3 Scalarization 249
 - 8.3 The Multi-criteria Dolph Problem for Arrays 250
 - 8.3.1 The Weak Dolph Problem 251
 - 8.3.2 Two Multi-criteria Versions 253
 - 8.4 Null Placement Problems and Super-gain 262
 - 8.4.1 Minimal Pattern Deviation 264
 - 8.4.2 Power and Super-gain 270
 - 8.5 The Signal-to-noise Ratio Problem 278
 - 8.5.1 Formulation of the Problem and Existence of
Pareto Points 278
 - 8.5.2 The Lagrange Multiplier Rule 280
 - 8.5.3 An Example 282

- A Appendix** 285
 - A.1 Introduction 285
 - A.2 Basic Notions and Examples 286
 - A.3 The Lebesgue Integral and Function Spaces 292
 - A.3.1 The Lebesgue Integral 292
 - A.3.2 Sobolev Spaces 295
 - A.4 Orthonormal Systems 298
 - A.5 Linear Bounded and Compact Operators 300
 - A.6 The Hahn-Banach Theorem 307
 - A.7 The Fréchet Derivative 310
 - A.8 Weak Convergence 312

VIII Contents

A.9 Partial Orderings	315
References	319
Index	327