

Contents

<i>Preface</i>	<i>page</i> xiii
<i>Nomenclature</i>	xv
0 Historical introduction	1
0.01 Quaternions	1
0.02 Linear associative algebras	2
0.03 Matrices	3
0.04 Grassmann	3
0.05 Vector analysis	4
0.06 Invariance	4
0.07 Tensors	5
0.08 Holor notation	6
0.09 Derivatives	7
0.10 Outline of the book	8
I Holors	
1 Index notation	11
1.01 Variety of holors	12
1.02 Notation	14
1.03 Conventions	15
1.04 The transpose	18
1.05 Symmetry and antisymmetry	19
1.06 Diagonal holors	21
1.07 Generalized Kronecker deltas	22
1.08 Summary	26
Problems	27

2 Holor algebra	30
2.01 Equality of holors	30
2.02 Addition of holors	32
2.03 The uncontracted product	36
2.04 The contracted product	40
2.05 Matrices	43
2.06 Index balance	45
2.07 Unit holors	47
2.08 The inverse	49
2.09 General conditions for an inverse	55
2.10 Null products	57
2.11 Cancellation rule for products	59
2.12 Summary	59
Problems	61
3 Gamma products	65
3.01 Change of index positions	66
3.02 Change of valence	67
3.03 Symmetric and antisymmetric matrices	69
3.04 Products of univalent holors	72
3.05 Nilvalent products	75
3.06 Univalent products	76
3.07 Alternating currents	78
3.08 Bivalent products	80
3.09 Other products	81
3.10 Summary	83
Problems	83
II Transformations	
4 Tensors	89
4.01 Linear transformations	89
4.02 Invariants	91
4.03 Groups	94
4.04 General transformations	95
4.05 Geometric objects	97
4.06 Univalent tensors	99
4.07 Other tensors	100
4.08 Tensor algebra	105
4.09 Tensor equations	108
4.10 Tensor character	111

4.11	Tensors with fixed merates	114
4.12	Summary	117
	Problems	119
5	Akinetors	126
5.01	Definitions	128
5.02	Algebra	129
5.03	The akinetor as generalization of the tensor	131
5.04	Combinations	134
5.05	Derivatives	136
5.06	Combinations of derivatives	139
5.07	Pseudodivergence	141
5.08	Pseudocurl	143
5.09	Other akinetors	145
5.10	Summary	148
	Problems	152
6	Geometric spaces	156
6.01	Arithmetic space	157
6.02	Invariants	158
6.03	Transformations	160
6.04	Affine space	162
6.05	Parting	165
6.06	Ratios of areas and of volumes	167
6.07	Second-degree surfaces	168
6.08	Axonometric space	170
6.09	Homogeneous coordinates	178
6.10	The projective transformation	180
6.11	Projective space	181
6.12	Perspective space	189
6.13	Inversions	193
6.14	Homogeneous coordinates in affine space	195
6.15	Bivalent tensors in affine space	197
6.16	Summary	203
	Problems	203
III Holor calculus		
7	The linear connection	211
7.01	The linear connection	213
7.02	The covariant derivatives of a contravariant vector	215
7.03	The covariant derivatives of a covariant vector	218

7.04	The covariant derivatives of bivalent tensors	219
7.05	Covariant derivatives of tensors of valence m	222
7.06	Contracted covariant derivatives	229
7.07	Derivatives with respect to a scalar parameter	232
7.08	The covariant derivatives of akinetors	234
7.09	Summary	238
	Problems	239
8	The Riemann–Christoffel tensors	242
8.01	Second covariant derivatives of scalars	242
8.02	Second covariant derivatives of contravariant vectors	243
8.03	Second covariant derivatives of covariant vectors	246
8.04	Second covariant derivatives of tensors	246
8.05	Second covariant derivatives of nilvalent akinetors	248
8.06	Second covariant derivatives of akinetors	249
8.07	Integrability of scalar fields	251
8.08	Integrability of contravariant vector fields	253
8.09	Integrability of covariant vector fields	256
8.10	Integrability of tensor fields	258
8.11	Integrability of nilvalent akinetor fields	260
8.12	Integrability of akinetor fields	262
8.13	Properties of the Riemann–Christoffel tensors	264
8.14	The Bianchi identities	266
8.15	Summary	268
	Problems	270

IV Space structure

9	Non-Riemannian spaces	275
9.01	The absolute differential	275
9.02	Homeomorphic displacements	279
9.03	The infinitesimal pentagon	282
9.04	Linearly connected spaces	285
9.05	Equations of paths	288
9.06	Parameter transformation	291
9.07	Weyl space	292
9.08	Projectively connected space	294
9.09	Projective invariants	296
9.10	Summary	297
	Problems	297

10 Riemannian space	300
10.01 The metric tensor	301
10.02 Modifications	304
10.03 The linear connection	308
10.04 Geodesics	314
10.05 Curvature	318
10.06 Homeomorphic transport of a vector	320
10.07 Volume and area	324
10.08 Scalar and vector products	326
10.09 Gradient, divergence, and curl	331
10.10 Theorems of Gauss and Stokes	336
10.11 The scalar and vector Laplacians	337
10.12 The contracted covariant derivative of a bivalent tensor	340
10.13 Summary	341
Problems	342
11 Euclidean space	346
11.01 Definition of Euclidean space	347
11.02 Metric coefficients	348
11.03 The linear connection	351
11.04 Rates and components	351
11.05 Euclidean n -space	353
11.06 Skew coordinates	354
11.07 Euclidean 3-space	358
11.08 Index notation versus vector notation	360
11.09 Sliding vectors	361
11.10 Sums of sliding vectors	365
11.11 Summary	369
Problems	370
<i>References</i>	376
<i>Index</i>	387