

CONTENTS

Preface	xi
Introduction	
1. The Weyl algebra	1
2. Algebraic D -modules	3
3. The book: an overview	5
4. Pre-requisites	6
Chapter 1. The Weyl algebra	
1. Definition	8
2. Canonical form	9
3. Generators and relations	10
4. Exercises	12
Chapter 2. Ideal structure of the Weyl algebra.	
1. The degree of an operator	14
2. Ideal structure	16
3. Positive characteristic	17
4. Exercises	18
Chapter 3. Rings of differential operators.	
1. Definitions	20
2. The Weyl algebra	22
3. Exercises	24
Chapter 4. Jacobian Conjecture.	
1. Polynomial maps	26
2. Jacobian conjecture	28
3. Derivations	30
4. Automorphisms	32
5. Exercises	34
Chapter 5. Modules over the Weyl algebra.	
1. The polynomial ring	36
2. Twisting	38
3. Holomorphic functions	40
4. Exercises	41

Chapter 6. Differential equations.	
1. The D -module of an equation	44
2. Direct limit of modules	46
3. Microfunctions	48
4. Exercises	50
Chapter 7. Graded and filtered modules.	
1. Graded rings	53
2. Filtered rings	55
3. Associated graded algebra	57
4. Filtered modules	59
5. Induced filtration	60
6. Exercises	62
Chapter 8. Noetherian rings and modules.	
1. Noetherian modules	65
2. Noetherian rings	67
3. Good filtrations	70
4. Exercises	72
Chapter 9. Dimension and multiplicity.	
1. The Hilbert polynomial	74
2. Dimension and multiplicity	77
3. Basic properties	80
4. Bernstein's inequality	82
5. Exercises	84
Chapter 10. Holonomic modules.	
1. Definition and examples	86
2. Basic properties	88
3. Further examples	91
4. Exercises	95
Chapter 11. Characteristic varieties.	
1. The characteristic variety	97
2. Symplectic geometry	100
3. Non-holonomic irreducible modules	104
4. Exercises	106
Chapter 12. Tensor products.	
1. Bimodules	108
2. Tensor products	109
3. The universal property	111

4. Basic properties	113
5. Localization	117
6. Exercises	119
Chapter 13. External products.	
1. External products of algebras	121
2. External products of modules	122
3. Graduations and filtrations	124
4. Dimensions and multiplicities	127
5. Exercises	128
Chapter 14. Inverse Image.	
1. Change of rings	130
2. Inverse images	132
3. Projections	134
4. Exercises	135
Chapter 15. Embeddings.	
1. The standard embedding	138
2. Composition	139
3. Embeddings revisited	142
4. Exercises	144
Chapter 16. Direct images.	
1. Right modules	146
2. Transposition	147
3. Left modules	150
4. Exercises	153
Chapter 17. Kashiwara's theorem.	
1. Embeddings	154
2. Kashiwara's theorem	156
3. Exercises	160
Chapter 18. Preservation of holonomy.	
1. Inverse images	162
2. Direct images	165
3. Categories and functors	166
4. Exercises	170
Chapter 19. Stability of differential equations.	
1. Asymptotic stability	171
2. Global upper bound	173
3. Global stability on the plane	176
4. Exercises	178

Chapter 20. Automatic proof of identities.	
1. Holonomic functions	179
2. Hyperexponential functions	180
3. The method	183
4. Exercises	186
Coda	188
Appendix 1. Defining the action of a module using generators	191
Appendix 2. Local inversion theorem	194
References	197
Index	203