

Contents

1. Introduction	1
1.1 Introductory Background	4
1.2 Content	6
<hr/>	
Part I. Principles of Fault Diagnosis	
<hr/>	
2. Analytical Techniques-Based FDI	11
2.1 Approaches to Linear Systems	11
2.1.1 Parameter Estimation	11
2.1.2 Parity Relation	13
2.1.3 Observers	14
2.2 Approaches to Non-linear Systems	16
2.2.1 Parameter Estimation	17
2.2.2 Parity Relation	17
2.2.3 Observers	19
2.3 Robustness Issues	22
2.4 Concluding Remarks	29
3. Soft Computing-Based FDI	31
3.1 Neural Networks	32
3.1.1 Basic Structures	32
3.1.2 Neural Networks in FDI	39
3.2 Evolutionary Algorithms	41
3.2.1 Introduction to Evolutionary Computation	41
3.2.2 Evolutionary Algorithms in FDI Schemes	44
3.3 Concluding Remarks	45

Part II. State and Parameter Estimation Strategies

4. State Estimation Techniques for FDI	49
4.1 Extended Unknown Input Observer	49
4.1.1 Convergence Analysis and Design Principles	51
4.1.2 Convergence of the EUIO	52
4.1.3 Illustrative Example	56
4.2 Extended Unknown Input Observer Revisited	58
4.2.1 Convergence Analysis and Design Principles	61
4.2.2 Illustrative Examples	66
4.3 Design of Observers and Unknown Input Observers for Lipschitz Systems	66
4.3.1 Convergence Analysis	67
4.3.2 Design Procedures	71
4.3.3 Design of an Unknown Input Observer	74
4.3.4 Experimental Results	76
4.4 Concluding Remarks	81
5. Parameter Estimation-Based FDI	85
5.1 Experimental Design	86
5.2 Impedance Measurement and Diagnosis	88
5.2.1 Problem Formulation	89
5.2.2 Experimental Design	91
5.2.3 Inductive Impedance	95
5.2.4 Towards Robustness	96
5.2.5 Simulation Results	97
5.3 Concluding Remarks	100

Part III. Soft Computing Strategies

6. Evolutionary Algorithms	105
6.1 Model Design with Genetic Programming	106
6.1.1 Model Structure Determination Using GP	108
6.1.2 State-Space Representation of the System	112
6.2 Robustifying the EUIO with Genetic Programming	114
6.3 Robustifying the EUIO with the ESSS Algorithm	115
6.4 Experimental Result	119
6.4.1 State Estimation and Fault Diagnosis	119
6.4.2 Industrial Application	125
6.5 Concluding Remarks	132

7. Neural Networks	133
7.1 Robust Fault Detection with the Multi-layer Perceptron	134
7.1.1 Illustrative Example	139
7.1.2 Algorithms and Properties of D-OED for Neural Networks	141
7.1.3 Locally D-Optimum On-Line Sequential Design	153
7.1.4 Industrial Application.....	160
7.2 Robust Fault Detection with GMDH Neural Networks	163
7.2.1 Model Uncertainty in the GMDH Neural Network	165
7.2.2 Bounded-Error Approach.....	167
7.2.3 Synthesis of the GMDH Neural Network Via the BEA.....	172
7.2.4 Robust Fault Detection with the GMDH Model	175
7.2.5 Industrial Application.....	176
7.3 Concluding Remarks	182
8. Conclusions and Future Research Directions	185
Appendix	191
References	193
Index	205