CONTENTS

Preface xi

CHAPTER I. ALGEBRAIC PRELIMINARIES 1

1. Inner Product Spaces 1
2. Dual Vector Spaces 6
3. The Orthogonal Group (Algebraic Study) 11
4. Self-Adjoint Transformations and Bilinear Forms 20
5. Tensor Product of Vector Spaces 25
6. Euclidean Spaces 32

CHAPTER II. DIFFERENTIABLE STRUCTURES 37

1. Differentiable Mappings 37
2. Submanifolds of Euclidean Space 40
3. Matrix Lie Groups 42
4. Tangent Spaces 47
5. Cotangent Space 53
6. Vector Fields and Forms 57

7. Tensor Spaces, 2-Forms, and the d Operator 61

8. Analytic Machinery 68

CHAPTER III. MATRIX LIE GROUPS AND FRAME BUNDLES 74

1. Parallel Displacement and Group Parallelism 74

2. Induced Riemann Metric 82

3. Vector-Valued Forms 86

4. The Orthonormal Frame Bundle Over E^n 92

5. Left-Invariant Forms on Matrix Lie Groups 95

6. Equations of Structure of Matrix Lie Groups 100

7. Equations of Structure for $\mathfrak{F}_0$ 101

CHAPTER IV. DIFFERENTIAL INVARIANTS OF SURFACES AND CURVES 110

1. Existence of Orthonormal Vector Fields 110

2. The Second Fundamental Form 113

3. The Second Fundamental Form (Continued) 119

4. The Frenet Formula 126

5. Uniqueness Theorems for Curves and Surfaces 133

6. Gaussian Curvature Zero and Development of Curves 137

CHAPTER V. LOCAL THEORY OF SURFACES 145

1. Orthonormal Frames in Coordinate Neighborhoods 145

2. General Frames and Affine Connections 152

3. The Classical Approach to Surface Theory 161

4. Geodesics Revisited 162

5. Elementary Geometric Theorems 171

6. Geodesic Coordinates and Applications 178

7. Examples 193

CHAPTER VI. GLOBAL STUDY OF SURFACES 199

1. Global Behavior of Geodesics 199
2. Complete Riemann Surfaces 203
3. Complete Surfaces of Constant Curvature 214
4. Abstract Riemann Manifolds 221
5. Hyperbolic Geometry 223

CHAPTER VII. INTEGRATION OF FORMS AND THE GAUSS-BONNET THEOREM 237

1. Partition of Unity 237
2. Integration of Forms on Surfaces 244
3. Rotation Index of a Vector Field 254
4. An Introduction to Theorems of the Gauss-Bonnet Type 265

Index 269