CONTENTS

PREFACE			iii
ABBREVI	ATIONS	AND NOTATION	vii
CHAPTER	1	INTERNAL SYSTEM DESCRIPTION: THE STATE VECTOR EQUATION	1
	1.1	The Discrete-Time State Vector Equation	1
	1.2	Discrete-Time State Variable Diagrams	6
	1.3	The Continuous-Time State Vector Equation	11
	1.4	Continuous-Time State Variable Diagrams	15
	1.5	Change of Variables	18
	1.6	Distinct Eigenvalue Diagonal Form	19
	1.7	Discrete-Time State Vector Equation Solution	21
	1.8	Continuous-Time State Vector Equation Solution	24
		Problems	33
		Remarks and References	36
CHAPTER	2	COMPLETE REACHABILITY AND COMPLETE OBSERVABILITY	39
	2.1	Complete Reachability in the Continuous- Time Case	39
	2.2	Complete Observability in the Continuous-Time Case	43
	2.3	Complete Reachability in the Discrete- Time Case	46
	2.4	Complete Observability in the Discrete- Time Case	48
	2.5	Reachability and Observability Canonical Forms	49
		Problems	54
		Remarks and References	56

x CONTENTS

CHAPTER	3	EXTERNAL SYSTEM DESCRIPTION: INPUT/OUTPUT MAPS	59
	3.1	The Unit Pulse Response	59
	3.2	The z-Transform	60
	3.3	State Vector Equations and z-Transforms	71
	3.4	The Transfer Function	74
	3.5	The Block Diagram	77
	3.6	The Unit Impulse Response	80
	3.7	The s-Transform	81
	3.8	State Vector Equations and s-Transforms	87
	3.9	Transfer Functions and Block Diagrams	89
		Problems	91
		Remarks and References	93
CHAPTER	4	COMPLETE REALIZATION	99
	4.1	Examples of Complete Realizations	99
	4.2	Minimal Complete Realizations	103
		Problems	109
		Remarks and References	111
CHAPTER	5	STABILITY	113
	5.1	Asymptotic Stability	113
	5.2	Uniform Bounded Input Bounded Output Stability	114
	5.3	Equivalence of AS and UBIBOS	116
	5.4	Routh-Hurwitz Criterion	120
	5.5	The Discrete-Time Case	121
		Problems	124
		Remarks and References	126
CHAPTER	6	COMPLETE IDENTIFICATION	129
	6.1	Complete Identification from the Unit Pulse Response	130
	6.2	Other Approaches to Complete Identification	131
	6.3	Complete Identification in the Continuous Time Case	- 138

хi	CONTENTS

	6.4	Comments on Partial Identification	140
		Problems	142
		Remarks and References	143
CHAPTER	7	THREE SPECIAL TOPICS	147
	7.1	Time Delay Systems	147
	7.2	Sampled Data Systems	156
	7.3	Linearization	162
		Problems	168
		Remarks and References	171
INDEX			175