

Contents

<i>Preface</i>	v
Chapter 1 Mathematical Preliminaries	1
1.1 Introduction	1
1.2 Basic topological notions	1
1.2.1 Linear topological spaces	1
1.2.2 Sequences, nets and continuity	6
1.2.3 Convex and compact sets	7
1.3 Topological vector spaces	9
1.3.1 General topological vector spaces	9
1.3.2 Metric spaces	13
1.3.3 Inductive and projective limits of normed spaces	15
1.3.4 Banach spaces and Hilbert spaces	21
1.3.5 Operators in Banach spaces	23
1.4 Fixed point theorems	24
1.5 Measures and function spaces	26
1.5.1 Measures and integrals on the positive real line	26
1.5.2 The function spaces L_p	29
1.5.3 Real and complex measures	31
1.5.4 Indefinite integrals	32
1.6 Dual spaces	34
1.7 Notes	39
References	39
Chapter 2 Riemann Surfaces and the Generalized Principal of the Argument	40
2.1 Introduction	40
2.1.1 Paths in topological spaces	41
2.1.2 Homotopy	42
2.2 Complex integration and Cauchy's theorem	45
2.3 Riemann surfaces	48
2.4 Minimum contours and algebroid Riemann surfaces	55
2.5 Analytic functions and integration in algebroid Riemann surfaces	58
2.6 Singular points	63

2.7	The Generalized Principle of the Argument	72
	References	80
Chapter 3	Representation of Multipliers	82
3.1	Introduction	82
3.2	Representation of multipliers in L_2 and L_2^n	83
3.3	Convolution algebra $\mathcal{M}(\mathbb{R}_+)$	87
3.4	Representation of multipliers in L_1 and L_1^n	92
3.5	Representation of multipliers in L_∞	97
3.6	Representation theory in X_p -spaces	97
	3.6.1 Sequential convergence vector spaces	98
	3.6.2 Sequential inductive limit spaces	99
	3.6.3 The spaces X_p	104
	3.6.4 Multipliers in X_1, X_2, X_∞	105
	3.6.5 Space of transfer functions \mathcal{R}	108
	References	111
	Appendix 3.1: The theory of multipliers in L_∞	112
Chapter 4	Linear Input–Output Stability Theory	121
4.1	Introduction	121
4.2	General analytic formulation of stability	123
4.3	Graphical stability criteria for L_2 -systems	129
4.4	Graphical stability criteria for multivariable systems	135
4.5	Notes	140
	References	141
Chapter 5	Extended Space Theory in the Study of System Operators	143
5.1	Introduction	143
5.2	Fundamental results	144
5.3	Operators in extended spaces	147
5.4	Well posedness and feedback systems	151
5.5	Passivity in feedback systems	153
5.6	Theory of multipliers	161
5.7	Sectoricity	165
5.8	Notes	170
	References	170
Chapter 6	Stability of Nonlinear Multivariable Systems—Circle Criteria	172
6.1	Introduction	172
6.2	Small gain theorems	173
	6.2.1 Boundedness small gain theorem	178
6.3	Intermediate small gain theorem	184
6.4	Incremental gain theorem	191

6.5	An M -matrix stability criterion	203
6.6	System diagonalization and design	207
6.7	Notes	212
	References	213
Chapter 7	Stability of Nonlinear Multivariable Systems—Passivity Results	215
7.1	Passivity stability theorems	215
7.2	Off-axis circle criteria	223
	7.2.1 The linear operator $\hat{F}(j\omega)$ is normal	223
	7.2.2 The linear operator $\hat{F}(j\omega)$ is non-normal	227
	7.2.3 Determination of the sectors of $Q(F-\Phi)$ and Q	231
7.3	Off-axis circle criteria-multiplier factorization	235
7.4	Multivariable Popov criterion	248
7.5	Notes	254
	References	255
	<i>Bibliography</i>	259
	<i>Subject index</i>	265