

CONTENTS

Preface vii

- 1 Introduction 1**
 - 1.1 Types of nonlinearity 4
 - 1.2 Linear systems 9
 - 1.3 Aspects of nonlinear behaviour 11

- 2 State-Space Models 14**
 - 2.1 Existence and uniqueness 15
 - 2.2 Linearisation 17
 - 2.3 Autonomous systems 18
 - 2.4 The phase portrait 19
 - 2.5 Singular points 20
 - 2.6 Isoclines 26
 - 2.7 Limit cycles 29
 - 2.8 Strange attractors and chaos 35
 - 2.9 Exercises 43

- 3 Harmonic Analysis 47**
 - 3.1 Describing functions 49
 - 3.2 Oscillations in feedback systems 60
 - 3.3 Validity of the describing function approximation 66
 - 3.4 Forced systems 71
 - 3.5 Exercises 79

- 4 Piecewise-Linear Models 81**
 - 4.1 The Point transformation method 81
 - 4.2 Variable-structure systems 92
 - 4.3 Tsytkin's method for relay systems 96
 - 4.4 Calculation of Tsytkin functions 102
 - 4.5 Relay Systems with periodic inputs 105
 - 4.6 Exercises 106

5	Stability	107
5.1	Equilibria of autonomous systems	108
5.2	Lyapunov's methods	109
5.3	Construction of Lyapunov functions	112
5.4	Unstable equilibrium points	117
5.5	Stability of motion	120
5.6	Time-varying systems	123
5.7	Feedback system stability	124
5.8	Absolute stability	128
5.9	Input-output methods	133
5.10	Exercises	135
6	Control System Performance	137
6.1	Bounds on system variables	138
6.2	The exponential-input describing function	146
6.3	Dither	149
6.4	Effect of dither on feedback systems	154
6.5	Adaptive control	157
6.6	Exercises	162
7	Discrete-Time Systems	164
7.1	Nonlinear recurrence relations	165
7.2	Stability in discrete time	168
7.3	Sampled-data systems	171
7.4	Limit cycles in sampled systems	175
	<i>Appendix 1</i>	Notes and References 181
	<i>Appendix 2</i>	Solutions to Exercises 189
	<i>Subject Index</i>	214