Contents

Preface

Chapter **1** ***Introduction*** *1*

Chapter **2** ***Writing Differential Equations*** *4*

2-1 Introduction *4*
2-2 Mechanical Systems *4*
2-3 Hydraulic Systems *18*
2-4 Electric Systems *21*
2-5 A Thermal System *25*
2-6 An Ecological System *26*
2-7 A Political-Military System *29*
2-8 Conclusion *30*
Problems *30*

Chapter **3** ***Solving Differential Equations*** *40*

3-1 Introduction *40*
3-2 Solution of Homogeneous Equations *43*
3-3 Consideration of Initial Conditions *47*
3-4 Solution of Nonhomogeneous Equations *49*

3-5 Transient and Steady-State Responses *52*
3-6 Combining Simultaneous Equations *53*
3-7 Conclusion *53*
Problems *54*

Chapter 4 ***Linear Equations for Modeling Nonlinear Systems*** *57*

4-1 Introduction *57*
4-2 Examples of Nonlinearities *58*
4-3 Principles of Linearization *62*
4-4 Conclusion *73*
Problems *73*

Chapter 5 ***Introduction to Vibrations*** *80*

5-1 Introduction *80*
5-2 Basic Principles and Definitions *82*
5-3 Units *88*
5-4 Conclusion *90*
Problems *90*

Chapter 6 ***Free Vibration: Systems with a Single Degree of Freedom*** *96*

6-1 Introduction *96*
6-2 Undamped Free Vibration *97*
6-3 Damped Free Vibration *104*
6-4 Determination of Damping Ratio from Experimental Data *110*
6-5 Conclusion *112*
Problems *113*

Chapter 7 ***Forced Vibration: Systems with a Single Degree of Freedom*** *121*

7-1 Introduction *121*
7-2 Examples of Mechanical Vibrating Systems with Sinusoidal Inputs *122*
7-3 Frequency Response *125*

7-4 Vibration Caused by Rotating Unbalance *137*
7-5 Displacement Input Acting Through a Dashpot and Spring in Parallel *141*
7-6 Transmissibility *146*
7-7 Systems with Simultaneous Inputs at Two or More Frequencies *149*
7-8 Conclusion *153*
Problems *156*

Chapter 8 ***More Complex Single-Degree-of-Freedom Systems*** *166*

8-1 Introduction *166*
8-2 Determining the Degrees of Freedom of a Mechanical System *166*
8-3 Method of Analysis *169*
8-4 Equivalent Inertia, Damping, and Spring Rate *176*
8-5 Conclusion *178*
Problems *179*

Chapter 9 ***Vibrating Systems with More Than One Degree of Freedom*** *186*

9-1 Introduction *186*
9-2 Writing the Equations of Motion *186*
9-3 Two-Mass System Without Damping *191*
9-4 Two-Mass System with Damping *198*
9-5 Vibrating Systems with More Than Two Degrees of Freedom *202*
9-6 Conclusion *202*
Problems *203*

Chapter 10 ***Distributed Parameter Systems*** *209*

10-1 Introduction *209*
10-2 Rigorous Analysis of a Distributed Parameter System *211*
10-3 Beams with Other Boundary Conditions *218*

10-4 Conclusion *219*
Problems *219*

Chapter 11 **Critical Speeds of Rotors** *221*

11-1 Introduction *221*
11-2 Analysis of a Simple Lumped Parameter Rotor *222*
11-3 Effect of Compliance in Bearings and Bearing Mounts *226*
11-4 Other Critical Speed Considerations *229*
11-5 Similar Rotor Instability Phenomena *234*
11-6 Conclusion *235*
Problems *236*

Chapter 12 **Balance of Rotors** *242*

12-1 Introduction *242*
12-2 Static Balance *243*
12-3 Dynamic Balance *245*
12-4 Conclusion *251*
Problems *252*

Chapter 13 **The Feedback Control System** *256*

13-1 Introduction *256*
13-2 Home Heating Application *257*
13-3 Feedback Control Systems *258*
13-4 Conclusion *259*

Chapter 14 **System Response and Stability** *261*

14-1 Introduction *261*
14-2 Response of a Liquid-Level System *262*
14-3 First-Order System Response to a Step Input *264*
14-4 First-Order System Response to a Sinusoidal Input *266*

14-5 Second-Order System Response *270*
14-6 Response of Higher-Order Systems to Simple Sinusoidal Inputs *274*
14-7 The Concept of System Stability *275*
14-8 Conclusion *277*
Problems *277*

Chapter 15 **Control Actions** *284*

15-1 Introduction *284*
15-2 Proportional Control *285*
15-3 Integral Control *288*
15-4 Proportional-plus-Integral Control *291*
15-5 "Bang-Bang" Control *293*
15-6 Other Control Actions *297*
15-7 Conclusion *297*
Problems *298*

Chapter 16 **Block Diagrams** *303*

16-1 Introduction *303*
16-2 The Transfer Function *304*
16-3 The Block Diagram *307*
16-4 Block Diagram Algebra *308*
16-5 Liquid-Level Integral Control System Example *314*
16-6 Systems with Two or More Inputs *318*
16-7 Feedback Compensation *321*
16-8 Conclusion *323*
Problems *324*

Chapter 17 **State-Variable Formulation and Computer Solutions** *327*

17-1 Introduction *327*
17-2 State-Variable Formulation *328*
17-3 State-Space Trajectories *334*
17-4 Analog Computer Solutions *336*
17-5 Digital Computer Solutions *339*
17-6 Conclusion *344*
Problems *344*

Chapter 18 **Experimental Determination of System Dynamic Characteristics** 348

18-1 Introduction *348*
18-2 Test Equipment and Instrumentation *350*
18-3 Applying System Inputs *359*
18-4 Recording and Interpreting System Response *362*
18-5 Conclusion *371*
Problems *372*

Appendix A **Deflection of Beams** 376

Appendix B **Alternative Mathematical Expressions for Certain Harmonic Functions** 380

Appendix C **Solution of Equations** 383

Appendix D **Steady-State Solutions by Rotating-Vector and Complex-Number Techniques** 386

Appendix E **Rayleigh's Energy Method** 394

Appendix F **Decibel Conversion Table** 397

Appendix G **Routh's Criterion** 398

Bibliography 401

Index 403