

# Contents

PART 1	STATIC HYSTERON	1
1.	Short-memory transducer	1
1.1	Transducer	1
1.2	States of transducer	2
1.3	Some properties of transducers	3
1.4	Admissible inputs	4
1.5	Vibro-correctness	6
2.	Generalized play	6
2.1	Ordinary play	6
2.2	Generalized play with piecewise monotone inputs	8
2.3	Estimates	10
2.4	Generalized play with continuous inputs	14
2.5	Dependence of outputs upon initial states	15
2.6	Correctness of the definition of the play	16
2.7	Monotonicity	17
2.8	Periodic inputs	19
2.9	Inputs defined on the whole real axis	20
3.	Hysteron	22
3.1	Stop	22
3.2	Determining systems of curves	24
3.3	Piecewise monotone inputs	28
3.4	Passage to arbitrary continuous inputs	28
4.	Canonical representation of hysteron and proof of Theorem 3.2	30
4.1	Canonical hysteron	30

4.2	Canonical representation theorem	32
4.3	Proof of Theorem 3.2	35
4.4	Properties of hysteron	35
4.5	Rectification of hysteron	39
5.	Distances	40
5.1	Definition of distance	40
5.2	Estimates on differences of output signals	43
6.	Various input spaces	47
6.1	Statement of the problem	47
6.2	Spaces of continuously differentiable functions	48
6.3	Play in the space $S$ of absolutely continuous functions	50
6.4	Hysteron in the space $S$	51
6.5	Hysterons in spaces $H_\alpha$	53
6.6	Discontinuous inputs	54
6.7	Hysteron in the space of functions with bounded variation	56
6.8	Hysteron in Wiener spaces	57
PART 2	IDENTIFICATION THEOREM	59
7.	Identification problem	59
7.1	General identification problem	59
7.2	Prehysteron	61
7.3	Basic identification theorem	63
7.4	Concluding remarks	64
8.	Proof of Theorem 7.1	65
8.1	Singular points of the domain $\Omega(V)$	65
8.2	Construction of curves $\Pi(M)$	69
8.3	Construction of curves $\Phi_L, \Phi_R$	74
8.4	Completion of the proof of Theorem 7.1	75
9.	$\alpha$ -identifiability	78
9.1	Statement of the problem	78
9.2	Normal hysteron	79
9.3	Theorem on $\alpha$ -identification	80
9.4	A remark	81
10.	Approximate construction of hysteron	81

10.1	Distance between hysterons	81
10.2	Bounded inputs	86
10.3	Frames of hysterons	88
10.4	Approximation by operators different from hysterons	90
PART 3 VIBRO-CORRECT DIFFERENTIAL EQUATIONS AND VARIABLE HYSTERONS		94
11.	Necessary condition of vibro-correctness	94
11.1	Integrator	94
11.2	Simple examples	96
11.3	Necessary condition of vibro-correctness	97
11.4	Vibro-correctness in a point	102
12.	Sufficient condition of vibro-correctness	103
12.1	Main result	103
12.2	An auxiliary equation	105
12.3	A substitution	107
12.4	Proof of Theorem 12.1	109
12.5	Lemma on differential inequalities	110
12.6	Vibro-correctness on smooth inputs	111
13.	Vibro-solutions	113
13.1	Definition	113
13.2	Global vibro-correctness	115
13.3	Inputs on finite time interval	117
13.4	Inputs on infinite time interval	119
14.	Equations with constraints	122
14.1	Equations with discontinuous right-hand sides	122
14.2	Arbitrary continuous constraints	125
14.3	Vibro-correct equations with constraints	128
14.4	Properties of vibro-solutions to equations with constraints	132
14.5	Vibro-solutions of parametrized equations	134
15.	Variable hysteron	138
15.1	Description of hysteron by differential equations	138
15.2	Variable hysteron	139
15.3	Variable hysteron governed by differential equations	143
15.4	Infinitesimal hysteron	145
15.5	A special class of transducers	147

PART 4	MULTIDIMENSIONAL HYSTERONS	151
16.	Multidimensional play and stop defined on smooth inputs	151
16.1	A simple example	151
16.2	A general notion	154
16.3	Correctness of the definitions of play and stop	158
16.4	Properties of play and stop	160
16.5	On the classical solutions of equations with discontinuous right-hand sides	160
17.	Strictly convex characteristics	162
17.1	Vibro-correctness modulus	162
17.2	Hölder condition	164
17.3	Passage to continuous inputs	166
17.4	Strong convergence	167
17.5	Perturbation of characteristics	167
17.6	Vibro-correctness modulus and differential inclusions	170
17.7	Lower bound for vibro-correctness moduli	175
18.	Polyhedral characteristics	177
18.1	Basic theorems	177
18.2	Estimates of the Lipschitz constant	179
18.3	Proofs of Lemma 18.1 and Theorem 18.4	181
18.4	Proof of Theorem 18.3	184
18.5	Remarks	186
19.	Arbitrary convex characteristics	187
19.1	Vibro-correctness of play and stop	187
19.2	Estimate for the variation of output	189
19.3	Proof of Theorem 19.1	191
20.	Inputs with summable derivatives	193
20.1	Statement of the problem	193
20.2	Lipschitz condition	194
20.3	Remarks	196
21.	Vibro-correct equations with vector input	196
21.1	Statement of the problem	196
21.2	Frobenius condition	198
21.3	Necessary condition of vibro-correctness	200
21.4	Sufficient condition of vibro-correctness	204
21.5	Remarks	205

22.	Equations with vector inputs and smooth constraints	206
22.1	Constraints	206
22.2	Planar motion	208
22.3	Other descriptions	209
PART 5 DISCONTINUOUS NONLINEARITIES		212
23.	Static elements	212
23.1	Continuous characteristics	212
23.2	Elements with discontinuous characteristics	214
23.3	Estimates of outputs	216
23.4	Proper characteristics	219
23.5	Continuity on a fixed input	220
23.6	Additional remarks	221
24.	Elements with monotone characteristics	223
24.1	Cones	223
24.2	Special classes of cones	224
24.3	Monotone characteristics	226
24.4	Proof of Theorem 24.1	228
24.5	Proof of Theorem 24.2	230
24.6	Remarks	231
25.	Elements with multi-valued characteristics	233
25.1	Selection problem	233
25.2	General theorems on selectors	234
25.3	Monotone selectors	238
25.4	Measurable selectors	240
25.5	Input-output relations	241
26.	Closures of static element	243
26.1	Closure of transducer	243
26.2	Characteristic of the closure	244
26.3	Closure modulo a negligence class	247
26.4	Comments	248
27.	Weak closures and convexification procedure	249
27.1	Weak closures	249
27.2	Convexification	251
27.3	Weak closures and convexification of static element	252
27.4	Proof of Theorem 27.1	253
27.5	Proof of Theorem 27.2	257

27.6	Convexification of static element modulo negligence class	259
27.7	Examples of open nonlinear systems composed of static elements	260
28.	Relay	262
28.1	Ideal relay	262
28.2	Non-ideal relay	263
28.3	Periodic inputs	266
28.4	Closure of relay	268
28.5	Convexification of relay	269
28.6	Relay and "slow" controls	271
28.7	Discontinuous inputs	272
PART 6	SELF-MAGNETIZATION PHENOMENON	274
29.	Madelung's hysterons	274
29.1	Non-correct prehysteron	274
29.2	Periodic inputs	277
29.3	Madelung's prehysteron	277
29.4	Properties of Madelung's prehysteron	279
29.5	Madelung's hysteron	281
29.6	Discontinuous inputs with bounded variation	284
30.	Proofs of Theorems 29.1 and 29.2	285
30.1	Passage to classical solutions	285
30.2	Lemma on differential inequalities	288
30.3	Proof of Theorem 29.1	289
30.4	Proof of Theorem 29.2	293
31.	Response to small perturbations of the input	294
31.1	General scheme	294
31.2	Intensities	296
31.3	Construction of $\kappa$ -outputs to Madelung's hysteron	299
31.4	Construction of $\kappa$ -vibrosolutions to differential equations	304
31.5	Construction of $\kappa$ -outputs for hysterons	311
32.	Closure modulo sets of Wiener measure zero	311
32.1	A general scheme	311
32.2	Main theorem	312

32.3	Passage to integral equations	314
32.4	Equations with constraints	317
32.5	Implications for stochastic equations	317
PART 7 COMPLEX HYSTERESIS NONLINEARITIES		320
33.	Parallel connections and bundles of hysterons	320
33.1	Complex nonlinearities	320
33.2	Parallel connections	321
33.3	Completely controllable restrictions	323
33.4	Periodic inputs	326
33.5	An important example	330
33.6	Remarks	331
34.	Sequential connections of hysterons	332
34.1	Sequential connections and cascades	332
34.2	Sequential connections of plays and stops	335
34.3	Compensators	338
34.4	Complex connections	341
35.	Ishlinskii's material	342
35.1	Continual systems of hysterons	342
35.2	Ishlinskii's transducer	343
35.3	Loading and unloading functions	346
35.4	Normal states of Ishlinskii's transducer	351
35.5	Periodic inputs	354
35.6	Davidenkov's model	357
35.7	Controllable restrictions of Ishlinskii's bundles	358
36.	Properties of Ishlinskii's transducer	359
36.1	Continuity of Ishlinskii's operator	359
36.2	Correctness with respect to weight functions	363
36.3	Unilateral estimates	365
37.	Finite systems of relays	367
37.1	Block-diagrams with relays	367
37.2	Parallel connections and bundles of relays	367
37.3	Independent perturbations of inputs	369
37.4	General perturbation of input	370
38.	Continual systems of relays	371
38.1	Bundles of relays and CRS-transducers	371

38.2	Monotonicity of CRS-transducers	373
38.3	Demagnetization function	373
38.4	Periodic inputs	374
38.5	Evaluation of outputs	375
38.6	Vibro-correctness	377
38.7	Controllable restrictions	381
39.	Rheological models	384
39.1	Construction of the model	384
39.2	Graphs	386
39.3	Transducer M	389
39.4	Properties of the transducer M	391
39.5	Transducer W	393
39.6	Remarks	395
	Bibliographic comments	397
	References	400
	Subject index	407