

# Contents

Foreword	v
Preface	vii
Introduction: Libration Points and Station Keeping	1
0.1 The Neighborhood of Libration Points as a Useful Place for Spacecrafts	1
0.1.1 The Libration Points in the Restricted Three-body Problem . . .	1
0.1.2 The Libration Points in Perturbations of the Restricted Three-body Problem . . . . .	2
0.1.3 Possible Missions Around the Libration Points . . . . .	2
0.1.4 The Real Nominal Quasi-periodic Orbit . . . . .	3
0.2 Station Keeping of Libration Point Orbits . . . . .	4
0.2.1 Unstable Nominal Orbits . . . . .	4
0.2.2 Requirements for an On/off Control . . . . .	5
<b>Chapter 1 Bibliographical Survey</b>	<b>7</b>
1.1 Numerical Results for Three-dimensional Periodic Orbits Around $L_1$ , $L_2$ and $L_3$ . . . . .	7
1.1.1 References . . . . .	7
1.1.2 Equations. General Properties . . . . .	8
1.1.3 Linear Theory Around the Equilibrium Points . . . . .	9
1.1.4 Description of the Results . . . . .	11
1.2 Analytic Results for Halo Orbits Associated to $L_1$ , $L_2$ and $L_3$ . . . . .	24
1.2.1 References . . . . .	24
1.2.2 Equations of Motion . . . . .	25
1.2.3 Construction of Halo Periodic Solutions . . . . .	34
1.3 Motion Near $L_4$ and $L_5$ . . . . .	36
1.3.1 References . . . . .	36
1.3.2 The Triangular Equilibrium Points, Location and Stability . . .	37
1.3.3 Numerical Explorations . . . . .	40
1.3.4 Analytic Results . . . . .	42

1.4	Station Keeping . . . . .	45
1.4.1	References . . . . .	45
1.4.2	The Control of Libration Point Satellites . . . . .	46
1.4.2.1	Perturbations and Nominal Path Control . . . . .	47
1.4.2.2	Linear Feedback Control . . . . .	48
1.4.2.3	Station Keeping . . . . .	49
1.4.3	Station Keeping for a Translunar Station . . . . .	49
1.4.3.1	Dynamics . . . . .	50
1.4.3.2	Linear Control . . . . .	51
1.4.3.3	Effect of Errors . . . . .	53
1.4.4	Control of an Unstable Periodic Orbit . . . . .	53
1.4.5	Station Keeping for the ISEE-C. Algorithm and Results . . . . .	55
1.4.5.1	Mission Design . . . . .	55
1.4.5.2	The Algorithm . . . . .	56
1.4.5.3	A Posteriori Information on the Mission . . . . .	57
1.4.6	Additional Work . . . . .	57
<b>Chapter 2 Halo Orbits. Analytic and Numerical Study</b>		<b>59</b>
2.1	The Restricted Three-body Problem . . . . .	59
2.1.1	Description of the Problem . . . . .	59
2.1.2	Values Adopted for the Constants . . . . .	61
2.2	Analytic Determination of the Families of Halo Orbits for the Restricted Three-body Problem . . . . .	62
2.2.1	Introduction . . . . .	62
2.2.2	Analytic Computations . . . . .	63
2.2.3	Description of the Program for the Computation of the Analytic Halo Orbits . . . . .	68
2.2.3.1	Storage of the Elements . . . . .	68
2.2.3.2	The Series $M$ , $N$ and $P$ . . . . .	72
2.2.3.3	Addition of Series . . . . .	73
2.2.3.4	Multiplication of Series . . . . .	73
2.2.3.5	Computation of the Amount of Elements Used in the Program . . . . .	75
2.2.4	Results of the Analytic Computations . . . . .	78
2.3	Numerical Determination of the Families of Halo Orbits for the RTBP. Analysis of Bifurcations and Terminations . . . . .	93
2.3.1	Description of the Program for the Numerical Computation of Symmetric Periodic Orbits for the RTBP . . . . .	93
2.3.1.1	The Continuation Method . . . . .	93
2.3.1.2	Refinement . . . . .	94
2.3.1.3	Implementation . . . . .	95

2.3.2	Tables of Numerical Values of the Families of Halo Orbits Associated to $L_1$ and $L_2$ . . . . .	96
2.3.3	The Halo Families Associated to $L_3$ . . . . .	115
2.3.4	Interest of These Orbits for Spacecraft Missions . . . . .	119
2.3.4.1	Small Size Halo Orbits Related to $L_1$ and $L_2$ . . . . .	119
2.3.4.2	The Stable Zone of Halo Orbits in the $L_1$ and $L_2$ cases	120
2.3.4.3	The $L_3$ Case . . . . .	123
2.3.5	Bifurcations . . . . .	124
2.3.6	Termination of the Families of Halo Orbits. The Hill Problem.	
	The Rotating Two-body Problem . . . . .	126
2.3.6.1	Introduction . . . . .	126
2.3.6.2	The KS Transform . . . . .	127
2.3.6.3	Vertical Periodic Orbits for Hill's Problem. Local Analysis . . . . .	128
2.3.6.4	Hill's Problem Bifurcations. Perturbations Due to $\mu$ .	129
2.3.6.5	Numerical Results . . . . .	132
2.3.6.6	The Rotating Two-body Problem . . . . .	137
2.3.7	The Elliptic Restricted Three-body Problem . . . . .	140
2.4	References . . . . .	141

**Chapter 3 The Neighborhood of the Halo Orbits: Numerical Study and Applications 143**

3.1	Numerical Study of the Local Invariant Manifolds . . . . .	143
3.1.1	The First Order Variational Equations . . . . .	143
3.1.2	Floquet Theory for Halo Orbits. The Floquet Modes . . . . .	145
3.1.3	Numerical Computation of the Unstable and Stable Manifolds .	148
3.1.4	Numerical Computation of the Remaining Floquet Modes . . . .	149
3.1.5	Results of the Computations. Consequences and Discussion . . .	150
3.2	The Proposed Method for the On/off Control . . . . .	159
3.2.1	On/off Control Using Invariant Manifolds . . . . .	159
3.2.2	The Projection Factors . . . . .	160
3.2.3	A First Approach Towards the Optimal Maneuvers . . . . .	161
3.2.4	Numerical Computations of Projection Factors and Unitary Controls . . . . .	163
3.2.5	Discussion of Results: the Different Gains and the No Delay Rule	177
3.2.6	A Second Approach Towards the Optimal Maneuvers . . . . .	178
3.3	On the Use of Solar Radiation Pressure for Station Keeping . . . . .	179
3.3.1	Using Radiation Pressure: Applicability and Limitations . . . . .	179
3.3.2	On the Determination of Optimal Parameters . . . . .	179
3.3.3	The "Always Towards the Sun" Rule . . . . .	181
3.4	Globalization of the Invariant Manifolds . . . . .	184
3.4.1	The Computation of the Global Stable Manifold . . . . .	184

3.4.2	Results of Interest for the Transfer Orbit . . . . .	184
3.5	References . . . . .	188
<b>Chapter 4 Analytic Solution of the Variational Equations. Analytic Computations for Control Parameters</b>		<b>189</b>
4.1	Analytic Solution of the Variational Equations . . . . .	189
4.1.1	The Analytic Method . . . . .	189
4.1.2	Description of the Program to Do the Analytic Computations . .	194
4.1.3	Results and Numerical Tests . . . . .	196
4.1.4	The Resonance Between Modes and the Related Problems of Convergence . . . . .	197
4.2	Analytic Computations for Control Parameters . . . . .	204
4.2.1	The General Method to be Used . . . . .	204
4.2.2	On the Fast Computation of the Involved Parameters . . . . .	205
4.2.3	Description of the Program to Obtain the Control Parameters .	206
4.2.4	Comparison with Direct Numerical Computations . . . . .	207
4.3	References . . . . .	216
<b>Chapter 5 The Equations of Motion for Halo Orbits Under the Effect of Perturbations and Near Triangular Points</b>		<b>217</b>
5.1	Analysis of the Perturbations . . . . .	217
5.1.1	Description and Justification of the Method. The Problems of Dynamical Coherence . . . . .	217
5.1.2	Determination of the Magnitudes to be Associated to the Differ- ent Weights . . . . .	218
5.1.3	The Reference Systems and the Related Changes of Coordinates	220
5.1.4	A Program for the Simulation of the Solar System and the Com- putation of Residual Accelerations . . . . .	222
5.1.5	The Adopted Model for the Motion Near Halo Orbits in the Cases Under Consideration . . . . .	226
5.2	Equations of Motion for Perturbed Halo Orbits . . . . .	237
5.2.1	Introduction . . . . .	237
5.2.2	The Lagrangian in Ecliptic Coordinates . . . . .	237
5.2.3	The Collinear Points for the Sun–Barycenter Problem . . . . .	239
5.2.4	Expressions of the Lagrangian in Different Coordinate Systems .	240
5.2.5	The Lagrange Equations for the Sun–Barycenter Problem, Col- linear Points Case . . . . .	246
5.2.6	The Collinear Points in the Earth–Moon Problem: Several Ex- pressions for the Lagrangian . . . . .	250
5.2.7	The Lagrange Equations for the Earth–Moon Problem: Collinear Points . . . . .	253
5.3	Equations of Motion Near the Triangular Points . . . . .	254
5.3.1	The Triangular Points for the Sun–Barycenter Problem . . . . .	254

5.3.2	The Lagrangian in Normalized Coordinates with Origin at $L_4$ or $L_5$ . . . . .	255
5.3.3	The Lagrange Equations for the Sun–Barycenter Problem, Triangular Case . . . . .	256
5.3.4	The Equations in the Earth–Moon Problem . . . . .	258
5.4	Numerical Tests of the Equations of Motion . . . . .	259
5.4.1	Description of a Program to Check the Equations of Motion . . . . .	259
5.4.2	Numerical Results . . . . .	260
5.5	References . . . . .	264

**Chapter 6 Expansions Required for the Equations of Motion. Collinear Points Case** **265**

6.1	Analytic Expansion of the Coefficients Due to the Noncircular Motion of the Earth–Moon Barycenter . . . . .	266
6.1.1	The Coefficients Appearing in the Equations of Motion . . . . .	266
6.1.2	A Program for the Computation of the Coefficients . . . . .	267
6.1.3	Numerical Results and Tests . . . . .	268
6.2	Preliminary Exploration of the Functions to be Kept . . . . .	276
6.2.1	Expansion of the Perturbing Functions as Sum of Monomials in the Coordinates . . . . .	276
6.2.2	A Rough Exploration of the Functions to be Kept . . . . .	277
6.3	Computation of the Approximate Frequencies and Magnitudes of the Perturbations Using FFT . . . . .	278
6.3.1	The Functions to be Analyzed . . . . .	278
6.3.2	The Filtering Procedure for the Output of FFT . . . . .	279
6.3.3	Numerical Results . . . . .	279
6.3.4	The Identification of the Frequencies . . . . .	280
6.4	The Final Computation of the Perturbing Terms . . . . .	290
6.4.1	Determination of the Coefficients . . . . .	290
6.4.2	Conversion to a Suitable Form for the Equations of the Quasi-periodic Orbit. Numerical Results . . . . .	290
6.5	References . . . . .	304

**Chapter 7 The Quasi-periodic Orbits: Equations, Method of Solution and Results** **305**

7.1	The Final Equations of Motion for the Collinear Case . . . . .	305
7.1.1	Expansion of the Equations of Motion in a Suitable Form for the Integration . . . . .	305
7.1.2	A Program for Producing the Equations of Motion . . . . .	307
7.1.3	Results and Numerical Checks . . . . .	309
7.2	The Method of Solution of the Equations for the Quasi-periodic Orbit . . . . .	323
7.2.1	General Expression of the Equations. The Recurrent Procedure . . . . .	323
7.2.2	A Lindstedt–Poincaré Device for the Quasi-periodic Orbit . . . . .	324

7.2.3	Description of the Program to Obtain the Analytic Quasi-periodic Orbit . . . . .	326
7.3	The Results. Problems Related to Small Divisors . . . . .	329
7.3.1	Sample of Results in Several Cases . . . . .	329
7.3.2	The Problem of Small Divisors . . . . .	330
7.3.3	The Analytic Expression of the Nominal Orbit . . . . .	331
7.4	References . . . . .	344

## **Chapter 8 Numerical Refinement of the Quasi-periodic Orbit: The Final Numerical Determination of the Orbit and of the Projection Factors 345**

8.1	A Parallel Shooting Method for the Numerical Refinement of the Quasi-periodic Orbit . . . . .	345
8.1.1	The Input Parameters to Get the Nominal Orbit . . . . .	345
8.1.2	A First Shooting Procedure. Description of the Program Used to this End . . . . .	348
8.1.3	Numerical Results and Discussion of the First Procedure . . . . .	356
8.1.4	A Second Shooting Procedure . . . . .	358
8.1.5	Numerical Results and Discussion of the Second Procedure . . . . .	359
8.1.6	Comments on Different Shooting Approaches . . . . .	360
8.2	The Final Nominal Orbit and Projection Factors . . . . .	370
8.2.1	The Problem of the Floquet Modes for a Quasi-periodic Orbit . . . . .	370
8.2.2	The Adopted Procedure to Obtain the Projection Factors . . . . .	371
8.2.3	A Program for the Final Nominal Computations. Results and Discussion . . . . .	372
8.3	References . . . . .	379

## **Chapter 9 The On/off Control Strategy: Simulations and Discussion 381**

9.1	A Simulation Program for the Motion of the Controlled Spacecraft . . . . .	381
9.1.1	The Equations of Motion. Introduction of Random and Systematic Noise in the Solar Radiation Pressure Effect . . . . .	381
9.1.2	The Effect of Tracking Errors and Errors in the Execution of Maneuvers . . . . .	382
9.1.3	How to Decide When a Control Should be Applied . . . . .	383
9.1.4	Description of the Program . . . . .	384
9.2	Numerical Results of the Simulations . . . . .	385
9.2.1	A Summary of Results . . . . .	385
9.2.2	Discussion on the Effect of the Different Errors and Magnitudes . . . . .	390
9.3	The Feasibility of the Control Using Solar Radiation Pressure . . . . .	402
9.3.1	The Determination of the Maneuver Interval. Discussion of Feasibility . . . . .	402

9.3.2	Simulations of the Radiation Pressure Control. Results and Discussion . . . . .	403
<b>Chapter 10</b>	<b>Other Cases and Further Simulations</b>	<b>409</b>
10.1	The $L_3$ Case for the Sun–Barycenter Problem . . . . .	409
10.1.1	Computation of Initial Conditions . . . . .	409
10.1.2	Results of Simulations . . . . .	410
10.2	The $L_3$ Case for the Earth–Moon Problem . . . . .	410
10.2.1	Results of a Simulation . . . . .	410
10.3	The Triangular Cases for the Sun–Barycenter Problem . . . . .	413
10.3.1	The Adopted Model for the Motion Near $L_4$ and $L_5$ . . . . .	413
10.3.2	Development of the Simplified Equations of Motion . . . . .	415
10.3.3	Analytic Solution. On the Existence of Almost Tori . . . . .	419
10.3.4	Simulations Starting at the Instantaneous Equilibrium Point or with Suitable Initial Conditions . . . . .	420
10.4	Simulations for the Triangular Cases in the Earth–Moon Problem . . . . .	428
10.4.1	Results of the Simulations . . . . .	428
10.5	References . . . . .	430
<b>Chapter 11</b>	<b>Summary and Outlook</b>	<b>433</b>
11.1	Summary of the Achieved Results . . . . .	433
11.1.1	Concerning the Halo Orbits . . . . .	433
11.1.2	Concerning the Quasi-periodic Nominal Orbit . . . . .	435
11.1.3	Concerning Station Keeping . . . . .	436
11.2	Possible Extensions of the Work . . . . .	439
11.2.1	The Use of Better Models for the Solar System . . . . .	439
11.2.2	The Translunar Problem Using the Real Solar System . . . . .	439
11.2.3	Stable Manifolds and the Transfer Problem . . . . .	440
11.3	Theoretical Problems . . . . .	440
11.3.1	The Small Divisors Problem for Quasi-periodic Orbits . . . . .	440
11.3.2	The Large Size Orbits in the Halo Family: Analytic Study and Perturbation to a Quasi-periodic Orbit . . . . .	440
11.3.3	The Floquet Modes for a Quasi-periodic Orbit. Searching for an Analytic Approach . . . . .	441
	Acknowledgments	443