

CONTENTS

PREFACE	xi
INTRODUCTION	xiii
LIST OF SYMBOLS	xix
CHAPTER I	Valued Fields
1. Valuations	3
2. Complete Valued Fields	6
3. Normed Vector Spaces	8
4. Hensel's Lemma	10
5. Extensions of Valuations	17
6. Newton Polygons	24
7. The y -intercept Method	28
8. Ramification Theory	30
9. Totally Ramified Extensions	33
CHAPTER II	Zeta Functions
1. Logarithms	38
2. Newton Polygons for Power Series	41
3. Newton Polygons for Laurent Series	46
4. The Binomial and Exponential Series	49
5. Dieudonné's Theorem	53
6. Analytic Representation of Additive Characters	56
7. Meromorphy of the Zeta Function of a Variety	61
8. Condition for Rationality	71
9. Rationality of the Zeta Function	74
Appendix to Chapter II	76
CHAPTER III	Differential Equations
1. Differential Equations in Characteristic p	77
2. Nilpotent Differential Operators. Katz-Honda Theorem	81
3. Differential Systems	86
4. The Theorem of the Cyclic Vector	89

5. The Generic Disk. Radius of Convergence	92
6. Global Nilpotence. Katz's Theorem	98
7. Regular Singularities. Fuchs' Theorem	100
8. Formal Fuchsian Theory	102

CHAPTER IV Effective Bounds. Ordinary Disks

1. p -adic Analytic Functions	114
2. Effective Bounds. The Dwork–Robba Theorem	119
3. Effective Bounds for Systems	126
4. Analytic Elements	128
5. Some Transfer Theorems	133
6. Logarithms	138
7. The Binomial Series	140
8. The Hypergeometric Function of Euler and Gauss	150

CHAPTER V Effective Bounds. Singular Disks

1. The Dwork–Frobenius Theorem	155
2. Effective Bounds for Solutions in a Singular Disk: the Case of Nilpotent Monodromy. The Christol–Dwork Theorem: Outline of the Proof	159
3. Proof of Step V	168
4. Proof of Step IV. The Shearing Transformation	169
5. Proof of Step III. Removing Apparent Singularities	170
6. The Operators ϕ and ψ	173
7. Proof of Step I. Construction of Frobenius	176
8. Proof of Step II. Effective Form of the Cyclic Vector	180
9. Effective Bounds. The Case of Unipotent Monodromy	189

CHAPTER VI Transfer Theorems into Disks with One Singularity

1. The Type of a Number	199
2. Transfer into Disks with One Singularity: a First Estimate	203
3. The Theorem of Transfer of Radii of Convergence	212

CHAPTER VII Differential Equations of Arithmetic Type

1. The Height	222
2. The Theorem of Bombieri–André	226
3. Transfer Theorems for Differential Equations of Arithmetic Type	234

4. Size of Local Solution Bounded by its Global Inverse Radius	243
5. Generic Global Inverse Radius Bounded by the Global Inverse Radius of a Local Solution Matrix	254
CHAPTER VIII <i>G</i> -Series. The Theorem of Chudnovsky	
1. Definition of <i>G</i> -Series. Statement of Chudnovsky's Theorem	263
2. Preparatory Results	267
3. Siegel's Lemma	284
4. Conclusion of the Proof of Chudnovsky's Theorem	289
Appendix to Chapter VIII	300
APPENDIX I Convergence Polygon for Differential Equations	301
APPENDIX II Archimedean Estimates	307
APPENDIX III Cauchy's Theorem	310
BIBLIOGRAPHY	317
INDEX	321