TABLE OF CONTENTS

Page

CHAPTER 1 - INTRODUCTION

CHAPTER 2 - MATHEMATICAL PRELIMINARIES

2.1 Introduction. 5
2.2 Linear Vector Spaces. 6
2.3 Linear Operators. 15
2.4 Scalar Matrices 20
2.5 Polynomial Matrices 24
2.6 Concluding Remarks and References 36
Problems - Chapter 2. 38

CHAPTER 3 - THE STATE SPACE

3.1 Introduction. 44
3.2 State Representations 46
3.3 The Determination of e^{At} 58
3.4 Equivalent Systems. 62
3.5 Controllability and Observability 65
3.6 Controllable and Observable Companion Forms 77
3.7 Concluding Remarks and References 92
Problems - Chapter 3. 94

CHAPTER 4 - FREQUENCY DOMAIN REPRESENTATIONS

4.1 Introduction. 99
4.2 The Transfer Matrix 100
4.3 The Structure Theorem 105
4.4 Realization Theory (Time Domain Reduction). 114
4.5 Concluding Remarks and References 127
Problems - Chapter 4. 130

CHAPTER 5 - DIFFERENTIAL OPERATOR REPRESENTATIONS

5.1 Introduction. 134
5.2 Transfer and Equivalence Relations. 135
5.3 Differential Operator Controllability and Observability 153
5.4 Realization Theory (Frequency Domain Reduction) 158
5.5 System Invertibility and Functional Reproducibility 161
5.6 Concluding Remarks and References 177
Problems - Chapter 5. 182

CHAPTER 6 - LINEAR STATE VARIABLE FEEDBACK

6.1 Introduction. 190
6.2 Quadratic Optimization. 191
6.3 Pole Assignment via the Controllable Companion Form 196
6.4 Asymptotic State Estimation 205

Page

CHAPTER 6 - LINEAR STATE VARIABLE FEEDBACK

6.5 Concluding Remarks and References 221
Problems - Chapter 6. 223

CHAPTER 7 - FREQUENCY DOMAIN COMPENSATION

7.1 Introduction. 226
7.2 Frequency Domain Implications of State Feedback 227
7.3 Frequency Domain State Estimation and Feedback. 231
7.4 A General Compensation Technique. 250
7.5 Concluding Remarks and References 260
Problems - Chapter 7. 263

CHAPTER 8 - DESIGN OBJECTIVES

8.1 Introduction. 269
8.2 Arbitrary Pole Placement. 271
8.3 Decoupling. 287
8.4 Static Decoupling 305
8.5 Exact Model Matching. 316
8.6 Concluding Remarks and References 324
Problems - Chapter 8. 329

REFERENCES. 343

INDEX 351