

CONTENTS

Preface

Chapter 1	Solution of Linear Singular Systems	1
1-1.	Introduction	1
1-2.	Regularity of general singular systems	4
1-3.	Equivalence of singular systems	10
1-4.	State response	16
1-5.	Notes and references	22
Chapter 2	Time Domain Analysis	23
2-1.	State reachability	23
2-2.	Controllability, R-controllability and impulse controllability	29
2-3.	Observability, R-observability, and impulse observability	38
2-4.	Dual principle	46
2-5.	System decomposition	50
2-6.	Transfer matrix and minimal realization	57
2-7.	Notes and references	65
Chapter 3	Feedback Control	67
3-1.	State feedback	67
3-2.	Infinite pole placement	78
3-3.	Finite pole placement	87
3-4.	Pole structure under state feedback control	95
3-5.	Output feedback control	98
3-6.	Notes and references	101
Chapter 4	State Observation	102
4-1.	Singular state observer	102
4-2.	Normal state observer	106
4-3.	General structure of state observers	118
4-4.	Disturbance decoupling state observers	122
4-5.	State observer with disturbance estimation	128
4-6.	Notes and references	131
Chapter 5	Dynamic Compensation for Singular Systems	132
5-1.	Singular dynamic compensators	132
5-2.	Full-order normal compensators	136
5-3.	Reduced-order normal compensators	142

VIII

5-4. Singular compensators in output regulation systems	152
5-5. Normal compensators in output regulation systems	161
5-6. Notes and references	166
Chapter 6 Structurally Stable Compensation in Singular Systems	167
6-1. Structural stability in homogenous singular systems	168
6-2. Compensation function on structural stability via dynamic feedback	174
6-3. Structurally stable normal compensators	179
6-4. Structurally stable normal compensators in output regulation systems	184
6-5. Notes and references	196
Chapter 7 System Analysis via Transfer Matrix	197
7-1. Transfer matrix in singular systems	197
7-2. State feedback and transfer matrix: single-input single-output systems	201
7-3. State feedback and transfer matrix: multiinput multioutput systems	208
7-4. Singular input function observers	215
7-5. Normal input function observers	219
7-6. Decoupling control	224
7-7. Notes and references	230
Chapter 8 Introduction to Discrete-time Singular Systems	231
8-1. Finite discrete-time series	232
8-2. Solution, controllability and observability in discrete-time singular systems	239
8-3. State feedback and pole placement in discrete-time singular systems	245
8-4. State observation for discrete-time singular systems	250
8-5. Dynamic compensation for discrete-time singular systems	259
8-6. Notes and references	265
Chapter 9 Optimal Control	266
9-1. Introduction	266
9-2. Optimal regulation with quadratic cost functional	267
9-3. Time optimal control	272
9-4. Optimal control for discrete-time singular systems	275
9-5. Notes and references	284
Chapter 10 Some Further Topics	285
10-1. Large-Scale singular systems	285
10-2. Adaptive control	291
10-3. Stochastic singular systems	294
10-4. Notes and references	301
Appendix A Distribution and Dirac Function	302

Appendix B	Some Results in Matrix Theory	306
Appendix C	Some Results in Control Theory	310
Appendix D	List of Symbols and Abbreviations	313
Appendix E	Subject Index	316
Appendix F	Bibliography	320