

Contents

	Preface to Volume II	xi
18	Elementary Group Theory	1
	18.1 The group axioms; examples	1
	18.2 Elementary consequences of the axioms; further definitions	3
	18.3 Isomorphism	5
	18.4 Permutation groups	6
	18.5 Homomorphisms; normal subgroups	8
	18.6 Cosets	10
	18.7 Factor groups	10
	18.8 The Law of Homomorphism	11
	18.9 The structure of cyclic groups	11
	18.10 Translations, inner automorphisms	12
	18.11 The subgroups of \mathcal{S}_4	13
	18.12 Generators and relations; free groups	15
	18.13 Multiply periodic functions and crystals	16
	18.14 The space and point groups	17
	18.15 Direct and semidirect products of groups; symmorphic space groups	20
19	Continuous Groups	25
	19.1 Orthogonal and rotation groups	25
	19.2 The rotation group $SO(3)$; Euler's theorem	27
	19.3 Unitary groups	28

- 19.4 The Lorentz groups 29
- 19.5 Group manifolds 34
- 19.6 Intrinsic coordinates in the manifold of the rotation group 35
- 19.7 The homomorphism of $SU(2)$ onto $SO(3)$ 37
- 19.8 The homomorphism of $SL(2, \mathbb{C})$ onto the proper Lorentz group \mathcal{L}_p 38
- 19.9 Simplicity of the rotation and Lorentz groups 38

20 Group Representations I: Rotations and Spherical Harmonics 40

- 20.1 Finite-dimensional representations of a group 41
- 20.2 Vector and tensor transformation laws 41
- 20.3 Other group representations in physics 44
- 20.4 Infinite-dimensional representations 45
- 20.5 A simple case: $SO(2)$ 46
- 20.6 Representations of matrix groups on X^∞ 47
- 20.7 Homogeneous spaces 48
- 20.8 Regular representations 49
- 20.9 Representations of the rotation group $SO(3)$ 50
- 20.10 Tesseral harmonics; Legendre functions 53
- 20.11 Associated Legendre functions 55
- 20.12 Matrices of the irreducible representations of $SO(3)$; the Euler angles 57
- 20.13 The addition theorem for tesseral harmonics 59
- 20.14 Completeness of the tesseral harmonics 60

21 Group Representations II: General; Rigid Motions; Bessel Functions 62

- 21.1 Equivalence; unitary representations 62
- 21.2 The reduction of representations 63
- 21.3 Schur's Lemma and its corollaries 65
- 21.4 Compact and noncompact groups 66
- 21.5 Invariant integration; Haar measure 67
- 21.6 Complete system of representations of a compact group 71
- 21.7 Homogeneous spaces as configuration spaces in physics 72
- 21.8 M_2 and related groups 73
- 21.9 Representations of M_2 73
- 21.10 Some irreducible representations 74
- 21.11 Bessel functions 75
- 21.12 Matrices of the representations 76
- 21.13 Characters 77

22 Group Representations and Quantum Mechanics 80

- 22.1 Representations in quantum mechanics 80
- 22.2 Rotations of the axes 81
- 22.3 Ray representations 82
- 22.4 A finite-dimensional case 83

- 22.5 Local representations 83
- 22.6 Origin of the two-valued representations 84
- 22.7 Representations of $SU(2)$ and $SL(2, \mathbb{C})$ 85
- 22.8 Irreducible representations of $SU(2)$ 87
- 22.9 The characters of $SU(2)$ 89
- 22.10 Functions of z and \bar{z} 89
- 22.11 The finite-dimensional representations of $SL(2, \mathbb{C})$ 90
- 22.12 The irreducible invariant subspaces of X^∞ for $SL(2, \mathbb{C})$ 92
- 22.13 Spinors 93

23 Elementary Theory of Manifolds 96

- 23.1 Examples of manifolds; method of identification 96
- 23.2 Coordinate systems or charts; compatibility; smoothness 98
- 23.3 Induced topology 101
- 23.4 Definition of manifold; Hausdorff separation axiom 101
- 23.5 Curves and functions in a manifold 103
- 23.6 Connectedness; components of a manifold 104
- 23.7 Global topology; homotopic curves; fundamental group 105
- 23.8 Mechanical linkages: Cartesian products 111

24 Covering Manifolds 114

- 24.1 Definition and examples 114
- 24.2 Principles of lifting 117
- 24.3 Universal covering manifold 119
- 24.4 Comments on the construction of mathematical models 121
- 24.5 Construction of the universal covering 123
- 24.6 Manifolds covered by a given manifold 125

25 Lie Groups 129

- 25.1 Definitions and statement of objectives 130
- 25.2 The expansions of $\mathfrak{m}(\cdot, \cdot)$ and $\mathfrak{l}(\cdot, \cdot)$ 132
- 25.3 The Lie algebra of a Lie group 133
- 25.4 Abstract Lie algebras 135
- 25.5 The Lie algebras of linear groups 135
- 25.6 The exponential mapping; logarithmic coordinates 136
- 25.7 An auxiliary lemma on inner automorphisms; the mappings Ad_μ 139
- 25.8 Auxiliary lemmas on formal derivatives 141
- 25.9 An auxiliary lemma on the differentiation of exponentials 143
- 25.10 The Campbell–Baker–Hausdorff (CBH) formula 144
- 25.11 Translation of charts; compatibility; G as an analytic manifold 146
- 25.12 Lie algebra homomorphisms 149
- 25.13 Lie group homomorphisms 151
- 25.14 Law of homomorphism for Lie groups 155
- 25.15 Direct and semidirect sums of Lie algebras 160
- 25.16 Classification of the simple complex Lie algebras 162
- 25.17 Models of the simple complex Lie algebras 167
- 25.18 Note on Lie groups and Lie algebras in physics 170
- Appendix to Chapter 25—Two nonlinear Lie groups 171

26	Metric and Geodesics on a Manifold	174
26.1	Scalar and vector fields on a manifold	175
26.2	Tensor fields	180
26.3	Metric in Euclidean space	182
26.4	Riemannian and pseudo-Riemannian manifolds	183
26.5	Raising and lowering of indices	185
26.6	Geodesics in a Riemannian manifold	186
26.7	Geodesics in a pseudo-Riemannian manifold	190
26.8	Geodesics; the initial-value problem; the Lipschitz condition	190
26.9	The integral equation; Picard iterations	192
26.10	Geodesics; the two-point problem	193
26.11	Continuation of geodesics	194
26.12	Affinely connected manifolds	195
26.13	Riemannian and pseudo-Riemannian covering manifolds	197
27	Riemannian, Pseudo-Riemannian, and Affinely Connected Manifolds	198
27.1	Topology and metric	199
27.2	Geodesic or Riemannian coordinates	199
27.3	Normal coordinates in Riemannian and pseudo-Riemannian manifolds	202
27.4	Geometric concepts; principle of equivalence	203
27.5	Covariant differentiation	206
27.6	Absolute differentiation along a curve	208
27.7	Parallel transport	209
27.8	Orientability	210
27.9	The Riemann tensor, general: Laplacian and d'Alembertian	211
27.10	The Riemann tensor in a Riemannian or pseudo-Riemannian manifold	214
27.11	The Riemann tensor and the intrinsic curvature of a manifold	216
27.12	Flatness and the vanishing of the Riemann tensor	218
27.13	Eisenhart's analysis of the Stäckel systems	221
28	The Extension of Einstein Manifolds	223
28.1	Special relativity	223
28.2	The Einstein gravitational field equations	224
28.3	The Schwarzschild charts	227
28.4	The Finkelstein extensions of the Schwarzschild charts	231
28.5	The Kruskal extension	233
28.6	Maximal extensions; geodesic completeness	235
28.7	Other extensions of the Schwarzschild manifolds	235
28.8	The Kerr manifolds	237
28.9	The Cauchy problem	240
28.10	Concluding remarks	243
29	Bifurcations in Hydrodynamic Stability Problems	244
29.1	The classical problems of hydrodynamic stability	244
29.2	Examples of bifurcations in hydrodynamics	245
29.3	The Navier–Stokes equations	247

29.4	Hilbert space formulation	248
29.5	The initial-value problem; the semiflow in \mathfrak{S}	248
29.6	The normal modes	249
29.7	Reduction to a finite-dimensional dynamical system	250
29.8	Bifurcation to a new steady state	254
29.9	Bifurcation to a periodic orbit	255
29.10	Bifurcation from a periodic orbit to an invariant torus	257
29.11	Subharmonic bifurcation	261
	Appendix to Chapter 29—Computational details for the invariant torus	261
30	Invariant Manifolds in the Taylor Problem	263
30.1	Survey of the Taylor problem to 1968	263
30.2	Calculation of invariant manifolds	265
30.3	Cylindrical coordinates	268
30.4	The Hilbert space	270
30.5	Separation of variables in cylindrical coordinates	271
30.6	Results to date for the Taylor problem	272
	Appendix to Chapter 30—The matrices in Eagles' formulation	274
31	The Early Onset of Turbulence	276
31.1	The Landau–Hopf model	276
31.2	The Hopf example	278
31.3	The Ruelle–Takens model	279
31.4	The ω -limit set of a motion	280
31.5	Attractors	282
31.6	The power spectrum for motions in \mathbb{R}^n	283
31.7	Almost periodic and aperiodic motions	284
31.8	Lyapounov stability	285
31.9	The Lorenz system; the bifurcations	286
31.10	The Lorenz attractor; general description	288
31.11	The Lorenz attractor; aperiodic motions	290
31.12	Statistics of the mapping f and g	293
31.13	The Lorenz attractor; detailed structure I	294
31.14	The symbols $[i, j]$ of Williams	297
31.15	Prehistories	299
31.16	The Lorenz attractor; detailed structure II	300
31.17	Existence of 1-cells in F	301
31.18	Bifurcation to a strange attractor	302
31.19	The Feigenbaum model	303
	Appendix to Chapter 31 (Parts A–H)—Generic properties of systems:	304
31.A	Spaces of systems	304
31.B	Absence of Lebesgue measure in a Hilbert space	304
31.C	Generic properties of systems	305
31.D	Strongly generic; physical interpretation	305
31.E	Peixoto's theorem	306
31.F	Other examples of generic and nongeneric properties	306
31.G	Lack of correspondence between genericity and Lebesgue measure	308
31.H	Probability and physics	308

References 313

Index 317