

Contents

Keynote Presentations

1. Swarm Robotics: The Coordination of Robots via
Swarm Intelligence Principles.....1
Marco Dorigo
2. Immuno-engineering.....3
*Jon Timmis, Emma Hart, Andy Hone, Mark Neal, Adrian Robins,
Susan Stepney and Andy Tyrrell*

Inspiration Based on Insect Behaviors

3. Heuristics for Uninformed Search Algorithms in Unstructured
P2P Networks Inspired by Self-Organizing Social Insect Models19
Prithviraj Dasgupta and Erik Antonson
4. Congestion Control in Ant Like Moving Agent Systems 33
Alexander Scheidler, Daniel Merkle and Martin Middendorf
5. Resource-Aware Clustering of Wireless Sensor Networks
Based on Division of Labor in Social Insects 45
Tales Heimfarth, Dalimir Orfanus and Flávio Rech Wagner

Sensors, Actuators and Networks

6. Self-Stabilizing Automata 59
Torben Weis and Arno Wacker
7. Experiments with Biologically-Inspired Methods for
Service Assignment in Wireless Sensor Networks 71
Tales Heimfarth and Peter Janacik

Robotics and Multi-Agent Systems

8. Evolving Collision Avoidance on Autonomous Robots 85
Lukas König and Hartmut Schmeck
9. Local Strategies for Connecting Stations by Small Robotic Networks... 95
Friedhelm Meyer auf der Heide and Barbara Schneider
10. Measurement of Robot Similarity to Determine the Best Demonstrator
for Imitation in a Group of Heterogeneous Robots 105
*Raphael Golombek, Willi Richert, Bernd Kleinjohann
and Philipp Adelt*
11. Distributed Fault-Tolerant Robot Control Architecture Based on
Organic Computing Principles 115
Adam El Sayed Auf, Marek Litza and Erik Maehle

Immunocomputing and Biological-Inspiration

12. Intrusion Detection via Artificial Immune System:
A Performance-based Approach 125
Andrea Visconti, Nicoló Fusi and Hooman Tahayori
13. Immuno-repairing of FPGA designs 137
Norma Montealegre, Franz J. Rammig
14. An Organic Computing Approach to Sustained
Real-time Monitoring 151
Rainer Buchty, David Kramer and Wolfgang Karl

Applications

15. A Case Study in Model-driven Synthetic Biology 163
*David Gilbert, Monika Heiner, Susan Rosser, Rachael Fulton,
Xu Gu and Maciej Trybilo*
16. Image Segmentation by a Network of Cortical Macrocolums with
Learned Connection Weights 177
Markus Lessman and Rolf P. Würtz
17. Integrating Emotional Competence into Man-Machine
Collaboration 187
Natascha Esau, Lisa Kleinjohann and Bernd Kleinjohann

Hardware Issues

18. Self-optimized Routing in a Network-on-a-Chip 199
*Wolfgang Trumler, Sebastian Schlingmann, Theo Ungerer,
Jun Ho Bahn and Nader Bagherzadeh*
19. On Robust Evolution of Digital Hardware 213
*Tobias Knieper, Bertrand Defo, Paul Kaufmann
and Marco Platzner*

Collaboration

20. A Model of Self-Organizing Collaboration 223
Rumen Andreev
21. Guiding Exploration by Combining Individual Learning and
Imitation in Societies of Autonomous Robots 233
Willi Richert, Oliver Niehörster and Florian Klompaker

- Author Index** 245