

Contents

1	Introduction	1
2	Mathematical Modeling of Non-Newtonian Fluids	5
2.1	Motivation	5
2.2	Notation	6
2.3	Balance Equations	10
2.4	The Total Stress Tensor	12
2.5	Constitutive Equations	15
2.5.1	Rate of Deformation Tensor	16
2.5.2	Rate of Shear	19
2.5.3	General Principles for Constitutive Equations	20
2.5.4	Incompressible Pure Viscous Fluids	21
2.5.5	Other Models	23
2.6	Conclusion	26
3	Local Strong Solvability of Non-Newtonian Flow Problems	29
3.1	Notations	30
3.2	Preliminaries	30
3.2.1	Sectorial Operators	34
3.2.2	\mathcal{R} -Boundedness and Fourier Multipliers	36
3.2.3	\mathcal{H}^∞ -calculus	40
3.3	Existence Result for Generalized Newtonian Flows	44
3.3.1	Strong Ellipticity	46
3.3.2	The Linear Problem with Constant Coefficients	48
3.3.3	The Linear Problem with Variable Coefficients	54
3.3.4	The Nonlinear Problem	63
3.4	Related Work	68
4	Numerical Analysis of Two-phase Flows	73
4.1	Numerical Treatment of the Navier-Stokes Equations	74
4.1.1	Boundary Conditions	74

4.1.2	General Time Splitting Technique	75
4.1.3	Finite Volume Method	78
4.2	Numerical Treatment of Two-phase Flows	80
4.2.1	Notations for Two-phase Flows	80
4.2.2	Mathematical Modeling of Surface Tension	80
4.2.3	Interfacial Dirac-Distribution	82
4.2.4	Interfacial Jump Conditions	85
4.2.5	Numerical Treatment of the Interface	89
4.2.6	Interfacial Area	93
4.2.7	Surface Tension	96
4.3	Binary Droplet Collision: Experiment and Simulation	99
4.3.1	Experimental Setup	100
4.3.2	Admissibility of the Viscosity Function	101
4.3.3	Numerical Setup and Results	103
4.4	Existence of Strong Solutions for Two Phase Flows	108

List of Figures

1.1	Weissenberg Effect	1
2.1	Rotating Lid Effect	6
2.2	Extrudate Swell [BAH77]. (<i>left</i>) Newtonian. (<i>right</i>) Non-Newtonian.	6
2.3	Simple Steady Shear Flow	13
2.4	Stress tensor.	14
2.5	Meaning of the components of \mathbf{D}	18
2.6	Superposition of Deformation and Rotation	20
2.7	Stress S_{21} versus shear rate.	21
2.8	Relations among rheological equations of state [BAH77].	27
4.1	Decomposition of domain Ω in N control volumes Ω_i , $i = 1, \dots, N$	78
4.2	Staggered Grid.	79
4.3	Force on a line element $d\mathbf{s}$ on the interface $\Gamma(t)$	81
4.4	Domain decomposition for the derivation of the jump conditions.	86
4.5	Illustration of the VOF-variable f	91
4.6	Transition zone introduced by Brackbill	97
4.7	Experiment of a binary droplet collision [MRB ⁺ 02]	100
4.8	Viscosity of the experimental liquids.	101
4.9	Simulation of the binary droplet collision using non-Newtonian fluids	104
4.10	Collision Complex Diameter versus Time	105
4.11	Illustration of overwriting the VOF-variable.	106
4.12	Comparison of the viscosity and shear rate distribution.	107
4.13	Shear rate distribution in connection with the droplet shape	108