

Contents

Series Preface	vii
Preface	ix
1 Introduction	1
1.1 Background	1
1.2 The concept of energy flow	2
1.3 Exercises	5
Part I Electromechanics	7
2 Review of Classical Mechanics	9
2.1 Newton's second law	9
2.2 Rigid bodies	12
2.3 Deformable bodies	15
2.4 References	20
3 Fundamentals of Electromagnetics	22
3.1 Coulomb's law	22
3.2 Lorentz's law	25
3.3 Biot-Savart law	25
3.4 Faraday's law	26
3.5 Maxwell's equations	30
3.6 Conservation of charge	32
3.7 Maxwell's equations (continued)	33
3.8 References	35

4 Electromagnetic Energy	36
4.1 Electrostatics	36
4.2 Electrostatic energy	38
4.3 Dielectrics	40
4.4 Magnetostatics	43
4.5 Ferromagnetics	44
4.6 Induction and inductance	48
4.7 Electromagnetic energy	51
4.8 Kirchhoff's laws	56
4.9 Maxwell's equations (revisited)	57
4.10 Exercises	59
4.11 References	60
5 Examples of Electric Machines	61
5.1 DC motors	61
5.2 Stepper motors	66
5.3 Exercises	71
5.4 References	72
6 Introduction to Piezoelastics	74
6.1 Dynamics of elastic layer	76
6.2 Dynamics of dielectric layer	83
6.3 Dynamics of piezoelastic layer	84
6.4 Exercises	90
6.5 References	92
Part II Contromechanics	95
7 Review of Classical Control	97
7.1 Dynamic systems	97
7.2 Laplace transforms	100
7.3 Transfer functions	102
7.4 Time response	104
7.5 Feedback control	107
7.6 Other topics	111

7.7 Exercises	111
7.8 References	112
8 Poles and Zeros	114
8.1 Discrete systems	115
8.2 Continuous systems	122
8.3 Migration of zeros	126
8.4 Pole/zero pairing	131
8.5 Discrete systems (nonminimum phase)	134
8.6 Continuous systems (nonminimum phase)	138
8.7 Summary	150
8.8 Exercises	150
8.9 References	155
9 Residual Vibration	157
9.1 Point-to-point control	157
9.2 Necessary and sufficient condition	159
9.3 Relevance to existing techniques	160
9.4 Laplace domain synthesis technique	163
9.5 Minimum energy control	164
9.6 Minimum jerk control	172
9.7 Frequency band-limited control	175
9.8 Summary	180
9.9 Exercises	182
9.10 References	182
10 Active Damping	185
10.1 Background	185
10.2 Problem definition	186
10.3 Three-dimensional piezoelasticity	187
10.4 Laminated piezopolymer plate theory	190
10.5 Dynamics of a simple PVDF laminar	195
10.6 References	198

Part III Appendices	201
A Units and Constants	203
B Review of Vector Calculus	205
B.1 Differential vector calculus	205
B.2 Integral vector calculus	207
C Elasticity Tensor	211
C.1 Definition of tensors	211
C.2 Elasticity tensor	212
D Disk Drive Mechatronics	214
D.1 System description	214
D.2 Electromechanics: moving-coil actuator	215
D.3 Contromechanics: read/write head suspension	218
D.4 Contromechanics: track-seeking servo	223
D.5 References	228
Index	231