

Contents

Chapter I	
Modeling Dynamic Systems	1
Modeling Philosophy	1
Some Physical Principles	4
State Models	9
Some Systems Concepts	12
Use of State Models	16
Chapter II	
First Order Linear State Models	18
Some Systems Theory	18
Case Study 2-1: Radioactive Decay of Cesium	21
Case Study 2-2: Temperature in a Building	23
Case Study 2-3: An RC Circuit	25
Exercises	28
Chapter III	
Second Order Linear State Models	31
Some Systems Theory	31
Case Study 3-1: Ingestion and Metabolism of a Drug	38
Case Study 3-2: Mixing of a Salt Solution	42
Case Study 3-3: DC Motor	47
Case Study 3-4: A Bridged-T-Filter	54
Exercises	59

Chapter IV	
Higher Order Linear State Models	67
Some Systems Theory	67
Case Study 4-1: Reduction of Limestone by Heating	69
Case Study 4-2: Vertical Ascent of a Deep Sea Diver	72
Case Study 4-3: A Speedometer Mechanism	76
Case Study 4-4: Automobile Suspension System	79
Case Study 4-5: Magnetic Loudspeaker	83
Exercises	89
Chapter V	
First Order Nonlinear State Models	96
Some Systems Theory	96
Case Study 5-1: Management of a Fisheries Resource	99
Case Study 5-2: Liquid Level in a Leaky Tank	104
Case Study 5-3: High Temperature Oven	106
Case Study 5-4: Circuit with Diode	108
Exercises	111
Chapter VI	
Second Order Nonlinear State Models	116
Some Systems Theory	116
Case Study 6-1: Motion of a Boat Crossing a River	119
Case Study 6-2: Spread of an Epidemic	121
Case Study 6-3: Tunnel-Diode Circuit	124
Case Study 6-4: Underwater Launch of a Rocket	128
Case Study 6-5: A Study of Blood Sugar and Insulin Levels with Application to Diabetes	131
Exercises	136
Chapter VII	
Higher Order Nonlinear State Models	141
Some Systems Theory	141
Case Study 7-1: Continuous Flow Stirred Tank Chemical Reactor	143
Case Study 7-2: A Hot Air Balloon	147
Case Study 7-3: Motion of a Rocket Near Earth	152
Case Study 7-4: Electrostatic Microphone	158
Exercises	163

Chapter VIII	
Other Differential State Models	172
Case Study 8-1: Feedback Control of the Liquid Level in a Tank	173
Case Study 8-2: Automatic Regulation of Temperature in a Building	177
Case Study 8-3: Sampled Control of a Field Actuated Motor	180
Exercises	184
Chapter IX	
Discrete Time and State Models	187
Case Study 9-1: Occupancy in a Hospital Unit	188
Case Study 9-2: An Inventory Model	189
Case Study 9-3: Neuron Model	190
Case Study 9-4: Coin Operated Dispenser	192
Case Study 9-5: A Binary Communications Channel	193
Case Study 9-6: Discrete Population Model	196
Exercises	198
Appendix A	
Units, Dimensions, and Conversion Factors	201
Appendix B	
Laplace Transforms	203
Appendix C	
Routh-Hurwitz Criteria	207
Appendix D	
Linear Approximations	210
Appendix E	
Digital Computer Simulation and CSMP	212
References	242
Index	246