

# Contents

<b>Preface</b>	<b>xi</b>
<b>1 Diagonally Stable Structures in Systems and Computation</b>	<b>1</b>
1.1 Introduction . . . . .	1
1.2 Robust Stability of a Mechanical System . . . . .	5
1.3 The Lotka–Volterra Ecosystem Model . . . . .	8
1.4 Convergence of Asynchronous Computations . . . . .	11
1.5 Global Stability of Neural Networks . . . . .	15
1.6 Variable Structure Systems . . . . .	17
1.7 Existence of Diagonal-Type Liapunov Functions . . . . .	21
1.8 Notes and References . . . . .	23
<b>2 Matrix Diagonal and D-Stability</b>	<b>25</b>
2.1 Matrix Stability Concepts . . . . .	25
2.1.1 Basic Notation and Terminology . . . . .	28
2.1.2 Basic Results on Hurwitz Diagonal and D-Stability	31
2.2 Special Classes of Hurwitz Diagonally Stable Matrices .	40
2.3 Similarity for Hurwitz Diagonally Stable Matrices . . . .	46
2.4 Persistence of Diagonal Stability under Perturbations . .	48
2.5 Basic Results on Schur Diagonal and D-Stability . . . . .	50
2.6 A Matrix Polytopic View of Schur Diagonal and D-Stability	54
2.7 Special Classes of Schur Diagonally Stable Matrices . . .	58

2.7.1	Schur Diagonal and D-Stability for Two-by-Two Matrices . . . . .	63
2.7.2	Nonnegative Matrices . . . . .	65
2.7.3	Qualitatively Schur Stable Matrices . . . . .	72
2.8	Testing for Diagonal and D-Stability . . . . .	75
2.9	Notes and References . . . . .	83
2.10	Appendix: Summary of the Theory of the Liapunov Equation . . . . .	85
<b>3</b>	<b>Mathematical Models Admitting Diagonal-Type Liapunov Functions</b>	<b>90</b>
3.1	Classes of Nonlinearities and Diagonal-Type Liapunov Functions . . . . .	90
3.2	Continuous-Time State-Space Models and Stability Results	92
3.3	Seeking Hurwitz Diagonal Stability: State-Space Realization Procedures . . . . .	98
3.4	Discrete-Time State-Space Models and Stability Results	101
3.4.1	Discrete-Time Interval Systems . . . . .	108
3.5	Models for Asynchronous Systems . . . . .	115
3.6	Discrete-Time Systems with Delays . . . . .	119
3.7	Notes and References . . . . .	122
3.8	Appendix: Summary of Liapunov Stability Theory . . . . .	123
<b>4</b>	<b>Convergence of Asynchronous Iterative Methods</b>	<b>128</b>
4.1	What Are Asynchronous Iterative Methods? . . . . .	128
4.2	A Mathematical Model for Asynchronous Block-Iterations	130
4.2.1	Convergence Conditions for the Asynchronous Case	133
4.2.2	Convergence Conditions for the Synchronous Case	136
4.3	Asynchronous Iterations to Solve Almost Linear Equations	138
4.4	Parallel Asynchronous Team Algorithms . . . . .	144
4.5	Notes and References . . . . .	152
<b>5</b>	<b>Neural Networks, Circuits, and Systems</b>	<b>154</b>
5.1	Continuous-Time Hopfield-Tank Neural Networks . . . . .	154
5.1.1	A Global Stability Result . . . . .	156
5.1.2	Refinements of the Global Stability Result . . . . .	158
5.1.3	Persistence of Global Asymptotic Stability . . . . .	164
5.2	Discrete-Time Neural Networks . . . . .	166
5.3	Passive RLC Circuits . . . . .	170
5.4	Digital Filters in State-Space Description . . . . .	174
5.5	Two-Dimensional (2D) Dynamical Systems . . . . .	177
5.6	Trophic Chains and Communities with Vertical Structure	184
5.7	Notes and References . . . . .	190

<b>6</b>	<b>Interconnected Systems: Stability and Stabilization</b>	<b>192</b>
6.1	Diagonal Stability in the Large Scale Systems Approach	192
6.2	Absolute Stability of Interconnected Systems . . . . .	199
6.3	Linearly Interconnected Lur'e Systems . . . . .	203
6.4	Stabilization by Linear Feedback . . . . .	210
6.5	Decentralized Power-Frequency Control of Power Systems	219
6.6	Notes and References . . . . .	226
6.7	Appendix: Summary of the Large Scale Systems Approach	227
	<b>Epilogue</b>	<b>231</b>
	<b>References</b>	<b>232</b>
	<b>Index</b>	<b>257</b>