
Contents

Foreword	xiii
Preface	xv
Introduction	xvii
Index of notation	xix

Part 1. A Quick Introduction to Complex Analytic Functions

Chapter 1. The complex exponential function	3
§1.1. The series	3
§1.2. The function \exp is \mathbf{C} -derivable	4
§1.3. The exponential function as a covering map	7
§1.4. The exponential of a matrix	8
§1.5. Application to differential equations	10
Exercises	12
Chapter 2. Power series	15
§2.1. Formal power series	15
§2.2. Convergent power series	20
§2.3. The ring of power series	22
§2.4. \mathbf{C} -derivability of power series	23
§2.5. Expansion of a power series at a point $\neq 0$	25
§2.6. Power series with values in a linear space	26
Exercises	27

Chapter 3. Analytic functions	29
§3.1. Analytic and holomorphic functions	29
§3.2. Singularities	32
§3.3. Cauchy theory	33
§3.4. Our first differential algebras	36
Exercises	37
Chapter 4. The complex logarithm	39
§4.1. Can one invert the complex exponential function?	39
§4.2. The complex logarithm via trigonometry	40
§4.3. The complex logarithm as an analytic function	41
§4.4. The logarithm of an invertible matrix	42
Exercises	44
Chapter 5. From the local to the global	45
§5.1. Analytic continuation	45
§5.2. Monodromy	47
§5.3. A first look at differential equations with a singularity	50
Exercises	52
Part 2. Complex Linear Differential Equations and their Monodromy	
Chapter 6. Two basic equations and their monodromy	57
§6.1. The “characters” z^α	57
§6.2. A new look at the complex logarithm	70
§6.3. Back again to the first example	74
Exercises	75
Chapter 7. Linear complex analytic differential equations	77
§7.1. The Riemann sphere	77
§7.2. Equations of order n and systems of rank n	81
§7.3. The existence theorem of Cauchy	87
§7.4. The sheaf of solutions	89
§7.5. The monodromy representation	91
§7.6. Holomorphic and meromorphic equivalences of systems	95
Exercises	101
Chapter 8. A functorial point of view on analytic continuation: Local systems	103

§8.1.	The category of differential systems on Ω	103
§8.2.	The category $\mathcal{L}\mathfrak{s}$ of local systems on Ω	105
§8.3.	A functor from differential systems to local systems	107
§8.4.	From local systems to representations of the fundamental group	109
	Exercises	113
Part 3. The Riemann-Hilbert Correspondence		
Chapter 9.	Regular singular points and the local Riemann-Hilbert correspondence	117
§9.1.	Introduction and motivation	118
§9.2.	The condition of moderate growth in sectors	120
§9.3.	Moderate growth condition for solutions of a system	123
§9.4.	Resolution of systems of the first kind and monodromy of regular singular systems	124
§9.5.	Moderate growth condition for solutions of an equation	128
§9.6.	Resolution and monodromy of regular singular equations	132
	Exercises	135
Chapter 10.	Local Riemann-Hilbert correspondence as an equivalence of categories	137
§10.1.	The category of singular regular differential systems at 0	138
§10.2.	About equivalences and isomorphisms of categories	139
§10.3.	Equivalence with the category of representations of the local fundamental group	141
§10.4.	Matricial representation	142
	Exercises	144
Chapter 11.	Hypergeometric series and equations	145
§11.1.	Fuchsian equations and systems	145
§11.2.	The hypergeometric series	149
§11.3.	The hypergeometric equation	150
§11.4.	Global monodromy according to Riemann	153
§11.5.	Global monodromy using Barnes' connection formulas	157
	Exercises	159
Chapter 12.	The global Riemann-Hilbert correspondence	161
§12.1.	The correspondence	161

§12.2. The twenty-first problem of Hilbert	162
Exercises	166
Part 4. Differential Galois Theory	
Chapter 13. Local differential Galois theory	169
§13.1. The differential algebra generated by the solutions	170
§13.2. The differential Galois group	172
§13.3. The Galois group as a linear algebraic group	175
Exercises	179
Chapter 14. The local Schlesinger density theorem	181
§14.1. Calculation of the differential Galois group in the semi-simple case	182
§14.2. Calculation of the differential Galois group in the general case	186
§14.3. The density theorem of Schlesinger in the local setting	188
§14.4. Why is Schlesinger's theorem called a "density theorem"?	191
Exercises	192
Chapter 15. The universal (fuchsian local) Galois group	193
§15.1. Some algebra, with replicas	194
§15.2. Algebraic groups and replicas of matrices	196
§15.3. The universal group	199
Exercises	200
Chapter 16. The universal group as proalgebraic hull of the fundamental group	201
§16.1. Functoriality of the representation $\hat{\rho}_A$ of $\hat{\pi}_1$	201
§16.2. Essential image of this functor	203
§16.3. The structure of the semi-simple component of $\hat{\pi}_1$	207
§16.4. Rational representations of $\hat{\pi}_1$	213
§16.5. Galois correspondence and the proalgebraic hull of $\hat{\pi}_1$	214
Exercises	216
Chapter 17. Beyond local fuchsian differential Galois theory	219
§17.1. The global Schlesinger density theorem	220
§17.2. Irregular equations and the Stokes phenomenon	221
§17.3. The inverse problem in differential Galois theory	226

§17.4. Galois theory of nonlinear differential equations	227
Appendix A. Another proof of the surjectivity of $\exp : \text{Mat}_n(\mathbf{C}) \rightarrow \text{GL}_n(\mathbf{C})$	229
Appendix B. Another construction of the logarithm of a matrix	233
Appendix C. Jordan decomposition in a linear algebraic group	237
§C.1. Dunford-Jordan decomposition of matrices	237
§C.2. Jordan decomposition in an algebraic group	241
Appendix D. Tannaka duality without schemes	243
§D.1. One weak form of Tannaka duality	245
§D.2. The strongest form of Tannaka duality	246
§D.3. The proalgebraic hull of \mathbf{Z}	248
§D.4. How to use tannakian duality in differential Galois theory	251
Appendix E. Duality for diagonalizable algebraic groups	255
§E.1. Rational functions and characters	255
§E.2. Diagonalizable groups and duality	257
Appendix F. Revision problems	259
§F.1. 2012 exam (Wuhan)	259
§F.2. 2013 exam (Toulouse)	260
§F.3. Some more revision problems	263
Bibliography	267
Index	271