

Contents

List of Symbols	vii
Acronyms	xiii
1 Introduction	1
2 Motivation and General Aim of this Work	5
2.1 Numerical Modeling of Iron Losses	5
2.2 Ferromagnetic Materials and Measurements	12
2.3 General Aim and Motivation	14
3 Ferromagnetic Behavior at Various Spatial Scales	21
3.1 Phenomenology of Ferromagnetism at the Macroscopic Scale .	22
3.1.1 Magnetic Hysteresis and the Constitutive Law	22
3.1.2 Basic Thermodynamics for Magnetized Media	30
3.1.3 Magnetic Anisotropy	35
3.2 Phenomenology of Ferromagnetism at the Microscopic Scale .	40
3.2.1 Paramagnetism	40
3.2.1.1 Classical Paramagnetism	41
3.2.1.2 Quantum Mechanical Theory of Paramagnetism	44
3.2.2 Ferromagnetism	46
3.3 Phenomenology of Ferromagnetism at the Mesoscopic Scale . .	49
3.3.1 Domain Theory	50
3.3.1.1 Exchange Energy	53
3.3.1.2 Magneto-crystalline Anisotropy Energy	54
3.3.1.3 Magnetostatic Energy	56
3.3.1.4 External Field Energy	57

3.3.1.5	Magneto-elastic Energy	58
3.3.1.6	Compromise Solution - Random Energy Landscapes	59
3.3.2	The Role of Defects in the Irreversibility of the Magnetization Process	61
3.3.3	Power Loss under Alternating and Rotational Magnetization	66
3.3.3.1	Power Losses under Alternating Magnetization	66
3.3.3.2	Power Losses under Rotational Magnetization	69
4	Metrological Characterization	77
4.1	General Principles - Physical Background	77
4.1.1	Determination of Magnetic Polarization	80
4.1.2	Determination of Magnetic Field Strength	85
4.1.3	Closed Magnetic Circuit	89
4.1.4	Quasi-static Measurements	90
4.1.5	AC Measurements	91
4.2	Standardized Measurement Setups	92
4.2.1	Epstein Frame	92
4.2.2	Single Sheet Tester	96
4.3	Rotational Power Loss Tester	98
5	Energy-based Hysteresis Modeling	107
5.1	Fully-fledged Hysteresis Model	108
5.1.1	Energy Potential - Thermodynamic Basis	108
5.1.1.1	Empty Space Magnetization	109
5.1.1.2	Energy Conservation	109
5.1.1.3	Internal Energy and An hysteretic Saturation	110
5.1.2	Pinning Force and Magnetic Dissipation	111
5.1.3	Representing the Complex Energy Landscape - Two-Scale Model	115

5.1.3.1	Magnetic Anisotropy - Orthotropic Sheet Anisotropy	118
5.2	Constitutive Relationships and Update Rule	121
5.2.1	Update Rule	121
5.2.2	Simplified Update Rule	122
5.2.3	Variational Formulation (Isotropic Case)	123
5.2.4	Saturation Characteristic	124
5.3	Parameter Identification	127
5.4	Discrete Representation of $\omega(\kappa)$	132
5.5	Dual Hysteresis Relationship	134
6	Analysis of the Energy-Based Hysteresis Model	139
6.1	Model Properties	140
6.2	Identification of the Energy-Based Hysteresis Model	141
6.3	Predictive Power and Comparison with Established Hysteresis Models	145
6.3.1	Hysteresis Models	146
6.3.1.1	Jiles-Atherton Hysteresis Model	146
6.3.1.2	GRUCAD Hysteresis Model	147
6.3.1.3	Stop Hysteresis Model	148
6.3.1.4	Tellinen Hysteresis Model	149
6.3.1.5	Zirka-Moroz Hysteresis Model	150
6.3.2	Implementation and Parameter Identification	151
6.3.2.1	Implementation of Discussed Models	151
6.3.2.2	Parameter Identification Constraints	151
6.3.2.3	Parameter Identification Approaches	152
6.3.3	Results	153
6.3.4	Conclusion	159
6.4	Magnetic Anisotropy and Vector Hysteresis	162
6.5	Conclusion	167

7	1-D Cross Lamination Model	169
7.1	1-D Cross Lamination Model	171
7.1.1	FE Formulation	174
7.1.2	Comparison of Model Predictions with Standard Measured Data	176
7.1.3	Predictive Power	185
7.1.4	Sinusoidal- H vs. Sinusoidal- B	188
7.1.5	Conclusion	189
7.2	Parametric Magneto-dynamic Model	190
7.2.1	Theory and Mathematical Background	192
7.2.2	Voltage- and Current-driven Sinusoidal Waveforms	196
7.2.3	Voltage- and Current-driven Arbitrary Waveforms	198
7.3	Loss Separation	203
7.4	Conclusion	207
8	Pragmatic Alternatives - Simplified Models of Electrical Steel Sheets	209
8.1	Transient Magnetization Model	210
8.2	Improved Thin Sheet Model - Saturation Wave Model	213
8.2.1	Analysis of the saturation-wave model (SWM)	218
8.2.2	Analysis and Validation of the TSM-S	223
8.3	Conclusion	227
9	Two-Step Homogenization	229
9.1	Macroscale FE model	230
9.2	Homogenization Methods	231
9.3	Two-step Homogenization	232
9.4	Analysis	236
9.5	Application Examples	240
9.5.1	Permanent Magnet Synchronous Machine	242
9.5.1.1	Embedded Magnet Machine	242
9.6	Conclusion	245

10 Validation with 2-D FE Simulations	247
10.1 Benchmark Problem	248
10.1.1 Mesh-free Model	248
10.1.2 FE Formulation	249
10.1.3 Solving Process	251
10.1.4 Three-Limb Transformer	251
10.2 Conclusion	258
11 Conclusion and Outlook	261
A Vector Hysteresis - Results	263
B Microstructural Data	265
B.1 Orientation Distribution Functions	265
B.1.1 Surface	265
B.1.2 25 % Ablation	266
B.1.3 50 % Ablation - Half Thickness	267
B.1.4 Averaged Over the Thickness	268
B.2 Microsections	269
B.2.1 Surface	269
B.2.2 25 % Ablation	270
B.2.3 50 % Ablation - Half Thickness	271
C Magnetization Dynamics	272
C.1 Stored and Dissipated Power Density	272
C.2 Benchmarking Various Hysteresis Models	278
List of Literature	281
Own Publications	303
Résumé	318