

# Contents

<b>1</b>	<b>Introduction</b> .....	1
1.1	Background .....	1
1.2	Methods and Issues .....	3
1.2.1	Description of DOSs .....	3
1.2.2	Numerical Example .....	5
1.3	Problems Studied in This Book .....	6
1.3.1	SMC of DOSs .....	8
1.3.2	Delays in DOSs .....	9
1.3.3	Filter for DOSs .....	11
1.3.4	Finite Frequency DOSs .....	13
1.3.5	Networked Control via DOSs .....	15
1.4	Summary .....	18

## Part I SMC of DOSs

<b>2</b>	<b>Observer Based on SMC for DOSs</b> .....	21
2.1	Introduction .....	21
2.2	Problem Statement .....	22
2.3	Main Results .....	23
2.3.1	Stability Analysis of Sliding Mode .....	23
2.3.2	Observer Based on SMC .....	25
2.3.3	Reachability Analysis of Sliding Surfaces .....	29
2.4	Numerical Example .....	30
2.5	Summary .....	33
<b>3</b>	<b>Robust Adaptive SMC for Uncertain DOSs</b> .....	35
3.1	Introduction .....	35
3.2	Problem Formulation .....	36
3.3	Main Results .....	38
3.4	Numerical Example .....	43
3.5	Summary .....	46

## Part II Stabilization of DOSs with Time Delays

<b>4</b>	<b>Robust Stabilization for DOSs with Time-Varying Delays</b> .....	51
4.1	Introduction .....	51
4.2	Problem Statement .....	52
4.3	Main Results .....	53
4.4	Numerical Example .....	58
4.5	Summary .....	60
<b>5</b>	<b>Robust <math>H_\infty</math> Control for T-S Fuzzy DOSs with Time Delays</b> .....	61
5.1	Introduction .....	61
5.2	Problem Statement .....	62
5.3	Main Results .....	64
5.4	Numerical Examples .....	75
5.5	Summary .....	81

## Part III Filter Design for DOSs

<b>6</b>	<b>Robust <math>H_\infty</math> Filter for Markovian Jump DOSs with Time-Varying Delays</b> .....	85
6.1	Introduction .....	85
6.2	Problem Statement .....	86
6.3	Main Results .....	89
6.4	Numerical Example .....	97
6.5	Summary .....	98
<b>7</b>	<b>A Novel DOKF Design and Convergence Analysis</b> .....	99
7.1	Introduction .....	99
7.2	Problem Formulation .....	100
7.3	Main Results .....	102
	7.3.1 DOKF Design Approach .....	102
	7.3.2 Convergence Analysis .....	104
7.4	Experimental Results .....	109
7.5	Summary .....	118

## Part IV Finite Frequency Control of DOSs

<b>8</b>	<b>Strictly Positive Real Control for DOSs with a Low Frequency Range</b> .....	121
8.1	Introduction .....	121
8.2	Problem Statement .....	122
8.3	Main Results .....	124

8.4	Numerical Simulation .....	130
8.5	Summary .....	133
<b>9</b>	<b>Generalized Finite Frequency KYP Lemma and Applications to Fault Detection .....</b>	<b>135</b>
9.1	Introduction .....	135
9.2	Problem Statement .....	136
9.3	Frequency Rang Characterization .....	138
9.3.1	Frequency Restrictions .....	139
9.3.2	Gain Properties .....	144
9.4	Application to Fault Detection .....	145
9.4.1	Fault Detection Filter .....	146
9.4.2	Filter Algorithm .....	149
9.4.3	Threshold Design .....	149
9.5	Numerical Examples .....	150
9.6	Summary .....	154
 <b>Part V Networked Control Using DOSs</b>		
<b>10</b>	<b>Stability of Markovian Jump Systems over Networks .....</b>	<b>159</b>
10.1	Introduction .....	159
10.2	Problem Statement .....	160
10.3	Main Results .....	165
10.4	Numerical Example .....	171
10.5	Summary .....	174
<b>11</b>	<b>Stabilization of NCSs with Nonuniform Sampling Periods .....</b>	<b>175</b>
11.1	Introduction .....	175
11.2	Problem Statement .....	176
11.3	Main Results .....	180
11.3.1	Stabilization of NCSs .....	180
11.3.2	NCS with Packets Dropout .....	188
11.3.3	Invariant Sampling Periods Case .....	190
11.4	Numerical Examples .....	194
11.5	Summary .....	202
<b>12</b>	<b>Stabilization of NCSs by Using DOKF .....</b>	<b>203</b>
12.1	Introduction .....	203
12.2	Problem Statement .....	204
12.3	Main Results .....	212
12.3.1	DOKF for NCSs .....	212
12.3.2	Stabilization of NCSs .....	216
12.4	Numerical Example .....	222
12.5	Summary .....	230

<b>13 Stability Analysis of High Frequency NCSs</b> .....	231
13.1 Introduction .....	231
13.2 Problem Statement .....	232
13.3 Main Results .....	239
13.4 Experimental Results .....	249
13.5 Summary .....	253
<b>References</b> .....	255
<b>Index</b> .....	273