

Contents

Part I: Coordination for Perception, Coverage and Tracking

- Adaptive Multi-Robot Coverage of Curved Surfaces** 3
Andreas Breitenmoser, Hannes Sommer, Roland Siegwart
- Nonlinear Cyclic Pursuit Based Cooperative Target Monitoring** 17
Sangeeta Dandgade, Arpita Sinha
- High Resolution Atmospheric Sensing Using UAVs** 31
Bobby Hodgkinson, Doug Lipinski, Luqian Peng, Kamran Mohseni
- A Physics Inspired Finite State Machine Controller for Mobile Acoustic Arrays** 47
Thomas Apker, Eric Martinson
- Vision Based Mobile Target Geo-localization and Target Discrimination Using Bayes Detection Theory** 59
Rajnikant Sharma, Josiah Yoder, Hyukseong Kwon, Daniel Pack

Part II: Task Allocation and Coordination Strategies

- A Real World Coordination Framework for Connected Heterogeneous Robotic Systems** 75
Nicola Bezzo, Mike S. Anderson, Rafael Fierro, John Wood
- Optimizing for Transfers in a Multi-vehicle Collection and Delivery Problem** 91
Brian Coltin, Manuela Veloso
- Distributed Amorphous Ramp Construction in Unstructured Environments** 105
Nils Napp, Radhika Nagpal

On Segregative Behaviors Using Flocking and Velocity Obstacles	121
<i>Vinicius Graciano Santos, Mario F.M. Campos, Luiz Chaimowicz</i>	
Object Transportation by Granular Convection Using Swarm Robots	135
<i>Ken Sugawara, Nikolaus Correll, Dustin Reishus</i>	
Multi-Robot Control for Circumnavigation of Particle Distributions	149
<i>Sarah Tang, Dylan Shanzaki, Christopher G. Lowe, Christopher M. Clark</i>	
Part III: Modular Robots and Novel Mechanisms and Sensors	
A One-Hour Curriculum to Engage Middle School Students in Robotics and Computer Science Using Cubelets	165
<i>Nikolaus Correll, Chris Wailes, Scott Slaby</i>	
A Fast Coalition Structure Search Algorithm for Modular Robot Reconfiguration Planning under Uncertainty	177
<i>Ayan Dutta, Prithviraj Dasgupta, Jose Baca, Carl Nelson</i>	
Flexible Self-reconfigurable Robots Based on Thermoplastic Adhesives	193
<i>Fumiya Iida, Liyu Wang, Luzius Brodbeck</i>	
Self-assembly and Self-reproduction by an M-TRAN Modular Robotic System	205
<i>Haruhisa Kurokawa, Akiya Kamamura, Kohji Tomita</i>	
Self-assembly in Heterogeneous Modular Robots	219
<i>Wenguo Liu, Alan F.T. Winfield</i>	
Error-Tolerant Cyclic Sequences for Vision-Based Absolute Encoders	233
<i>Kevin C. Wolfe, Gregory S. Chirikjian</i>	
Arbitrary Lattice Formation with Flocking Algorithm Applied to Camera Tracking System	247
<i>Sho Yamauchi, Hidenori Kawamura, Keiji Suzuki</i>	
Part IV: Formation Control and Motion Planning for Robot Teams	
A Stochastic Optimal Enhancement of Feedback Control for Unicycle Formations	261
<i>Ross P. Anderson, Dejan Miliutinović</i>	

Maximum-Leaf Spanning Trees for Efficient Multi-Robot Recovery with Connectivity Guarantees	275
<i>Golnaz Habibi, James McLurkin</i>	
Multi-Robot Formation Morphing through a Graph Matching Problem	291
<i>Lantao Liu, Dylan A. Shell</i>	
Hexagonal Lattice Formation in Multi-Robot Systems	307
<i>Sailesh Prabhu, William Li, James McLurkin</i>	
Direct Policy Search with Variable-Length Genetic Algorithm for Single Beacon Cooperative Path Planning	321
<i>Tan Yew Teck, Mandar Chitre</i>	
Optimal Multi-Robot Path Planning with LTL Constraints: Guaranteeing Correctness through Synchronization	337
<i>Alphan Ulusoy, Stephen L. Smith, Calin Belta</i>	
Part V: Learning, Adaptation, and Cognition in Many Robot Systems	
Evolving Aggregation Behaviors in Multi-Robot Systems with Binary Sensors	355
<i>Melvin Gauci, Jianing Chen, Tony J. Dodd, Roderich Groß</i>	
Robot Teams: Sharing Visual Memories	369
<i>Raphael Grech, Francisco Flórez-Revueita, Dorothy N. Monekosso, Paolo Remagnino</i>	
Distributed Particle Swarm Optimization for Limited Time Adaptation in Autonomous Robots	383
<i>Ezequiel Di Mario, Alcherio Martinoli</i>	
A Multi-Robot Cognitive Sharing System Using Audio and Video Sensors	397
<i>Daniel McGibney, Ryo Morioka, Kosuke Sekiyama, Hiro Mukai, Toshio Fukuda</i>	
Conditional Random Fields for Behavior Recognition of Autonomous Underwater Vehicles	409
<i>Michael Novitzky, Charles Pippin, Thomas R. Collins, Tucker R. Balch, Michael E. West</i>	

Imitation Learning and Behavior Generation in a Robot Team	423
<i>Huan Tan</i>	
Supervised Learning in Robotic Swarms: From Training Samples to Emergent Behavior	435
<i>Gregory Vorobyev, Andrew Vardy, Wolfgang Banzhaf</i>	
Author Index	449