Table of Contents

Part 1. Vision and Dynamic Systems

Active Perception and Exploratory Robotics 3
R. Bajcsy

Object Identification and Search: Animate Vision Alternatives to Image Interpretation 21
M.J. Swain, L.E. Wixson, D.H. Ballard

A Model of Human Feature Detection Based on Matched Filters 43
M.C. Morrone, D.C. Burr

Visualizing and Understanding Patterns of Brain Architecture 65
A. Rojer, E.L. Schwartz

Dynamic Vision 89
H. Wechsler, L. Zimmerman

A Model of the Acquisition of Object Representations in Human 3D Visual Recognition 99
S. Edelman, D. Weinshall, H.H. Bülthoff, T. Poggio

Part 2. Hands and Tactile Perception

The Perception of Mechanical Stimuli Through the Skin of the Hand and Its Physiological Bases 121
R.T. Verrillo, S.J. Bolanowski, Jr.

Borrowing Some Ideas from Biological Manipulators to Design an Artificial One 139
V. Hayward

Mechanical Design for Whole-Arm Manipulation 153
W.T. Townsend, J.K. Salisbury

Whole-Hand Manipulation: Design of an Articulated Hand Exploiting All Its Parts to Increase Dexterity 165
G. Vassura, A. Bicchi

Stable Grasping and Manipulation by a Multifinger Hand with the Capability of Compliance Control 179
K. Tanie, M. Kaneko

Part 3. Locomotion

Mobile Robots – the Lessons from Nature 193
D.J. Todd

Quadruped Walking Machine – Creation of the Model of Motion 207
A. Morecki, T. Zielinska

Biped Locomotion by FNS: Control Issues and an ANN Implementation 223
G.F. Inbar

How Fast Can a Legged Robot Run? 239
J. Koechling, M.H. Raibert

Robot Biped Walking Stabilized with Trunk Motion 271
A. Takanishi

Part 4. Intelligent Motor Control

A New Concept of the Role of Proprioceptive and Recurrent Inhibitory Feedback in Motor Control 295
U. Windhorst

Analogic Models for Robot Programming 319
R. Zaccaria, P. Morasso, G. Vercelli

Structural Constraints and Computational Problems in Motor Control 339
F.A. Mussa-Ivaldi, E. Bizzi

Motion Control in Intelligent Machines 361
A. Meystel

Control of Contact in Robots and Biological Systems 395
N. Hogan

Motor Control Simulation of Time Optimal Fast Movement in Man 411
B. Hannaford, L. Stark

Constraints on Underspecified Target Trajectories 419
M.I. Jordan

Proposal for a Pattern Matching Task Controller for Sensor-Based Coordination of Robot Motions 445
M. Brooks

Sensory-Motor Mapping with a Sequential Network 457
L. Massone, E. Bizzi

Part 5. Design Technologies

Flexible Robot Manipulators and Grippers: Relatives of Elephant Trunks and Squid Tentacles 475
J.F. Wilson, D. Li, Z. Chen, R.T. George, Jr.

Progress in the Design and Control of Pseudomuscular Linear Actuators 495
G. Casalino, P. Chiarelli, D. De Rossi, G. Genuini, P. Morasso, M. Solari

Shape Memory Alloy Linear Actuators for Tendon-Based Biomorphic Actuating Systems 507
M. Bergamasco, F. Salsedo, P. Dario

CCD Retina and Neural Net Processor 535
A.M. Chiang

Retina-Like CCD Sensor for Active Vision 553
G. Sandini, P. Dario, D.M. De Micheli, M. Tistarelli

Designing Artificial Structures from Biological Models 571
M. Aizawa, H. Shinohara

Design Strategies for Gas and Odour Sensors Which Mimic the Olfactory System 579
K.C. Persaud, J. Bartlett, P. Pelosi

Part 6. Interfacing Robots to Nervous System

Multi-Electrode Stimulation of Myelinated Nerve Fibers 605
P.H. Veltink, J.A. van Alsté, J. Holsheimer

The Role of Materials in Designing Nerve Guidance Channels and Chronic Neural Interfaces 625
R.F. Valentini, P. Aebischer

Regeneration-Type Peripheral Nerve Interfaces for Direct Man/Machine Communication 637
G.T.A. Kovacs, J.M. Rosen

Integrated Bioelectronic Transducers 667
M. Grattarola, A. Cambiaso, S. Cenderelli, S. Martinoia, M.T. Parodi, M. Tedesco

Part 7. Robot Societies and Self-Organization

A Robot Being 679
R.A. Brooks, A.M. Flynn

Swarm Intelligence in Cellular Robotic Systems 703
G. Beni, J. Wang

A Control Architecture for Cooperative Intelligent Robots 713
J.S. Albus

Cellular Robotics – Construction of Complicated Systems from Simple Functions 745
T. Fukuda, Y. Kawauchi

List of Participants 783